

1.

7.2-4. (a)

$$\begin{aligned}x(t) &= \frac{1}{2\pi} \int_{-\omega_0}^{\omega_0} e^{-j\omega t_0} e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-\omega_0}^{\omega_0} e^{j\omega(t-t_0)} d\omega \\&= \frac{1}{(2\pi)j(t-t_0)} e^{j\omega(t-t_0)} \Big|_{-\omega_0}^{\omega_0} = \frac{\sin \omega_0(t-t_0)}{\pi(t-t_0)} = \frac{\omega_0}{\pi} \operatorname{sinc}[\omega_0(t-t_0)]\end{aligned}$$

(b)

$$\begin{aligned}x(t) &= \frac{1}{2\pi} \left[\int_{-\omega_0}^0 j e^{j\omega t} d\omega + \int_0^{\omega_0} -j e^{j\omega t} d\omega \right] \\&= \frac{1}{2\pi t} e^{j\omega t} \Big|_{-\omega_0}^0 - \frac{1}{2\pi t} e^{j\omega t} \Big|_0^{\omega_0} = \frac{1 - \cos \omega_0 t}{\pi t}\end{aligned}$$

2.

7.3-4. From time-shifting property

$$x(t \pm T) \iff X(\omega) e^{\pm j\omega T}$$

Therefore

$$x(t+T) + x(t-T) \iff X(\omega) e^{j\omega T} + X(\omega) e^{-j\omega T} = 2X(\omega) \cos \omega T$$

We can use this result to derive transforms of signals in Figure P7.3-4.

(a) Here $x(t)$ is a gate pulse as shown in Figure S7.3-4a.

$$x(t) = \operatorname{rect}\left(\frac{t}{2}\right) \iff 2 \operatorname{sinc}(\omega)$$

Also $T = 3$. The signal in Figure S7.3-4a is $\overline{x(t+3)} + \overline{x(t-3)}$, and

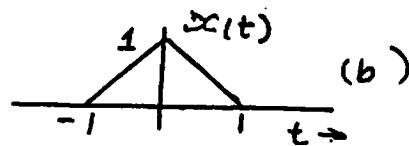
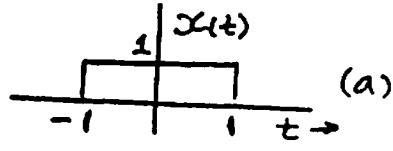
$$x(t+3) + x(t-3) \iff 4 \operatorname{sinc}(\omega) \cos 3\omega$$

(b) Here $x(t)$ is a triangular pulse shown in Figure S7.3-4b. From the Table 4.1 (pair 19)

$$x(t) = \Delta\left(\frac{t}{2}\right) \iff \operatorname{sinc}^2\left(\frac{\omega}{2}\right)$$

Also $T = 3$. The signal in Figure P7.3-4b is $\overline{x(t+3)} + \overline{x(t-3)}$, and

$$x(t+3) + x(t-3) \iff 2 \operatorname{sinc}^2\left(\frac{\omega}{2}\right) \cos 3\omega$$



3.

7.3-10. (a)

$$X(\omega) = \int_{-T}^0 e^{-j\omega t} dt - \int_0^T e^{-j\omega t} dt = -\frac{2}{j\omega} [1 - \cos \omega T] = \frac{j4}{\omega} \sin^2 \left(\frac{\omega T}{2} \right)$$

(b)

$$x(t) = \text{rect} \left(\frac{t+T/2}{T} \right) - \text{rect} \left(\frac{t-T/2}{T} \right)$$

$$\begin{aligned} \text{rect} \left(\frac{t}{T} \right) &\iff Ts \text{sinc} \left(\frac{\omega T}{2} \right) \\ \text{rect} \left(\frac{t \pm T/2}{T} \right) &\iff Ts \text{sinc} \left(\frac{\omega T}{2} \right) e^{\pm j\omega T/2} \end{aligned}$$

$$\begin{aligned} X(\omega) &= Ts \text{sinc} \left(\frac{\omega T}{2} \right) [e^{j\omega T/2} - e^{-j\omega T/2}] \\ &= 2jTs \text{sinc} \left(\frac{\omega T}{2} \right) \sin \frac{\omega T}{2} \\ &= \frac{j4}{\omega} \sin^2 \left(\frac{\omega T}{2} \right) \end{aligned}$$

(c)

$$\frac{df}{dt} = \delta(t+T) - 2\delta(t) + \delta(t-T)$$

The Fourier transform of this equation yields

$$j\omega X(\omega) = e^{j\omega T} - 2 + e^{-j\omega T} = -2[1 - \cos \omega T] = -4 \sin^2 \left(\frac{\omega T}{2} \right)$$

Therefore

$$X(\omega) = \frac{j4}{\omega} \sin^2 \left(\frac{\omega T}{2} \right)$$

4.

7.4-2. (a)

$$X(\omega) = \frac{1}{j\omega + 1} \quad \text{and} \quad H(\omega) = \frac{-1}{j\omega - 2}$$

and

$$Y(\omega) = \frac{-1}{(j\omega - 2)(j\omega + 1)} = \frac{1}{3} \left[\frac{1}{j\omega + 1} - \frac{1}{j\omega - 2} \right]$$

Therefore

$$y(t) = \frac{1}{3} [e^{-t}u(t) + e^{2t}u(-t)]$$

(b)

$$X(\omega) = \frac{-1}{j\omega - 1} \quad \text{and} \quad H(\omega) = \frac{-1}{j\omega - 2}$$

and

$$Y(\omega) = \frac{1}{(j\omega - 1)(j\omega - 2)} = \frac{-1}{j\omega - 1} - \frac{-1}{j\omega - 2}$$

Therefore

$$y(t) = [e^t - e^{2t}]u(-t)]$$

5.

$$\begin{aligned} a) H(\omega) &= \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC} \\ &= \frac{1}{RC} \left(\frac{1}{\frac{1}{RC} + j\omega} \right) \end{aligned}$$

From line 1 of the F.T. table

$$h(t) = \frac{1}{RC} e^{-\frac{1}{RC}t} u(t) \quad (\text{same as HW2 prob2}).$$

$$b) \text{ When } x(t) = u(t) \quad X(\omega) = \pi\delta(\omega) + \frac{1}{j\omega}$$

(from line 11 of the table on page 702).

hence

$$\begin{aligned} Y(\omega) &= H(\omega) X(\omega) = \frac{\pi\delta(\omega) + \frac{1}{j\omega}}{1 + j\omega RC} \\ &= \frac{\pi\delta(\omega)}{1 + j\omega RC} + \frac{\frac{1}{j\omega}}{1 + j\omega RC} \end{aligned}$$

Since the inverse F.T. is linear, we can compute the inverse F.T.'s of these terms individually...

(continued)

$$\mathcal{F}^{-1} \left\{ \frac{\pi \delta(\omega)}{1+j\omega RC} \right\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\pi \delta(\omega)}{1+j\omega RC} e^{j\omega t} d\omega = \frac{\pi}{2\pi} = \frac{1}{2}$$

↑
sifting
property

$$\begin{aligned}\mathcal{F}^{-1} \left\{ \frac{\frac{1}{j\omega}}{1+j\omega RC} \right\} &= \mathcal{F}^{-1} \left\{ \left(\frac{1}{j\omega} \right) \cdot \left(\frac{1}{1+j\omega RC} \right) \right\} \\ &= \mathcal{F}^{-1} \left\{ \frac{a}{j\omega} + \frac{b}{1+j\omega RC} \right\}\end{aligned}$$

$$a(1+j\omega RC) + b(j\omega) = 1$$

$$\begin{aligned}\Rightarrow a &= 1 \\ b &= -RC\end{aligned}$$

$$\mathcal{F} \left\{ \frac{1}{j\omega} \right\} - \mathcal{F} \left\{ \frac{RC}{1+j\omega RC} \right\} = \underbrace{\frac{1}{2} \operatorname{sgn}(t)}_{\substack{\uparrow \\ \text{line 12} \\ \text{of table}}} - \underbrace{e^{-\frac{1}{RC}t} u(t)}_{\substack{\uparrow \\ \text{line 1} \\ \text{of table.}}}$$

Put it all together:

$$y(t) = \underbrace{\frac{1}{2} + \frac{1}{2} \operatorname{sgn}(t)}_{= u(t)} - e^{-\frac{1}{RC}t} u(t)$$

$$y(t) = (1 - e^{-\frac{1}{RC}t}) u(t)$$

same answer as HW2
problem 2.