

# ECE503 Homework Assignment Number 7 Solution

Due by 8:50pm on Monday 26-Mar-2012

1. 3 points. Suppose a discrete-time signal

$$x[n] = \begin{cases} 0.9^n & n = 0, \dots, 9 \\ 0 & \text{otherwise.} \end{cases}$$

is sent through an ideal reconstruction filter with sampling period  $T = \frac{1}{10}$  seconds to generate a continuous-time signal  $x(t)$ .

- (a) Note that  $x[n] = 0$  for all  $n < 0$ . Does  $x(t) = 0$  for all  $t < 0$ ? Why or why not?

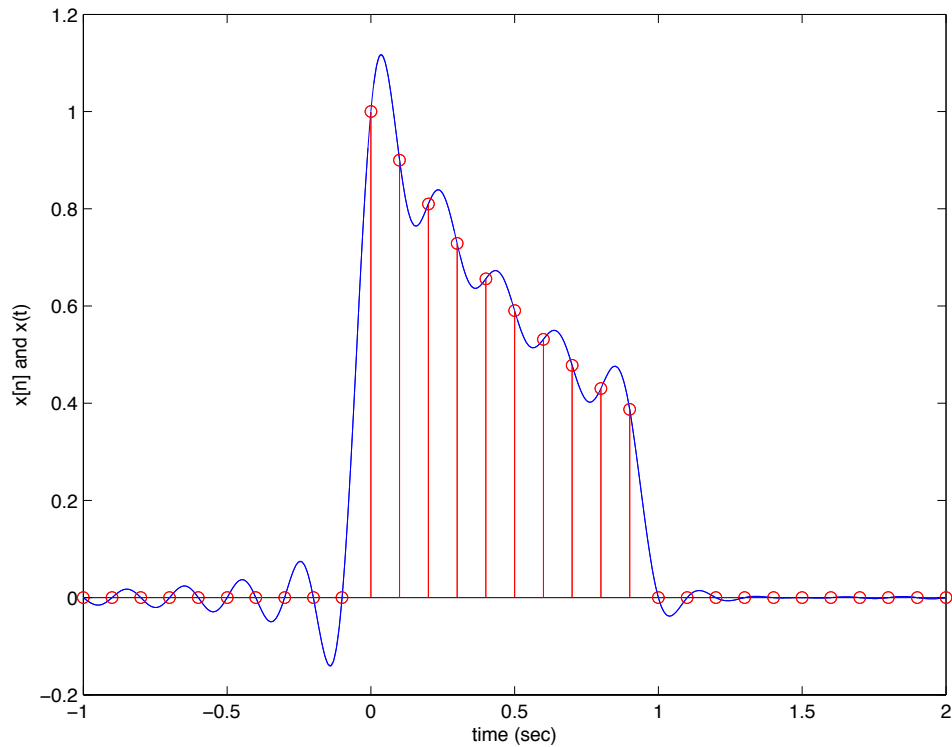
**Solution:** The ideal reconstruction formula states

$$\begin{aligned} x(t) &= \sum_{n=-\infty}^{\infty} x[n] \frac{\sin(\pi(t - nT)/T)}{\pi(t - nT)/T} \\ &= \sum_{n=0}^9 0.9^n \frac{\sin(10\pi(t - n/10))}{10\pi(t - n/10)}. \end{aligned}$$

To see that  $x(t)$  is not equal to zero for all  $t < 0$ , let's pick, for example,  $t = -1/20$ . Then

$$\begin{aligned} x(t = -1/20) &= \sum_{n=0}^9 0.9^n \frac{\sin(10\pi(-1/20 - n/10))}{10\pi(-1/20 - n/10)} \\ &= \sum_{n=0}^9 0.9^n \frac{\sin(-\pi/2 - n\pi)}{-\pi/2 - n\pi} \\ &= \sum_{n=0}^9 0.9^n \frac{\sin(\pi/2 + n\pi)}{\pi/2 + n\pi} \\ &\approx 0.5036 \end{aligned}$$

The following figure shows  $x(t)$  and  $x[n]$  as related by the ideal interpolation formula when  $T = \frac{1}{10}$  seconds.



```

tt = -1:0.0001:2;
T = 1/10;
n = 0:9;
alpha = 0.9;
x = zeros(1,length(tt));
i1 = 0;
for t = tt,
    i1 = i1+1;
    x(i1) = sum((alpha.^n).*sin(pi*(t-n*T)/T)./(pi*(t-n*T)/T));
end
plot(tt,x);
hold on
stem(-1:T:2,[zeros(1,10) 0.9.^n zeros(1,11)],'r');
xlabel('time (sec)');
ylabel('x[n] and x(t)')

```

- (b) Determine the value of  $x(t)$  at time  $t = 0.5$  seconds.

**Solution:** The ideal reconstruction formula states

$$\begin{aligned}
 x(t) &= \sum_{n=-\infty}^{\infty} x[n] \frac{\sin(\pi(t-nT)/T)}{\pi(t-nT)/T} \\
 &= \sum_{n=0}^9 0.9^n \frac{\sin(10\pi(0.5-n/10))}{10\pi(0.5-n/10)} \\
 &= \sum_{n=0}^9 0.9^n \frac{\sin(5\pi-n\pi)}{5\pi-n\pi}
 \end{aligned}$$

Note

$$\frac{\sin(5\pi - n\pi)}{5\pi - n\pi} = \begin{cases} 1 & n = 5 \\ 0 & n \neq 5. \end{cases}$$

So

$$\begin{aligned} x(t) &= \sum_{n=0}^{\infty} 0.9^n \delta[n - 5] \\ &= 0.9^5 \approx 0.5905 \end{aligned}$$

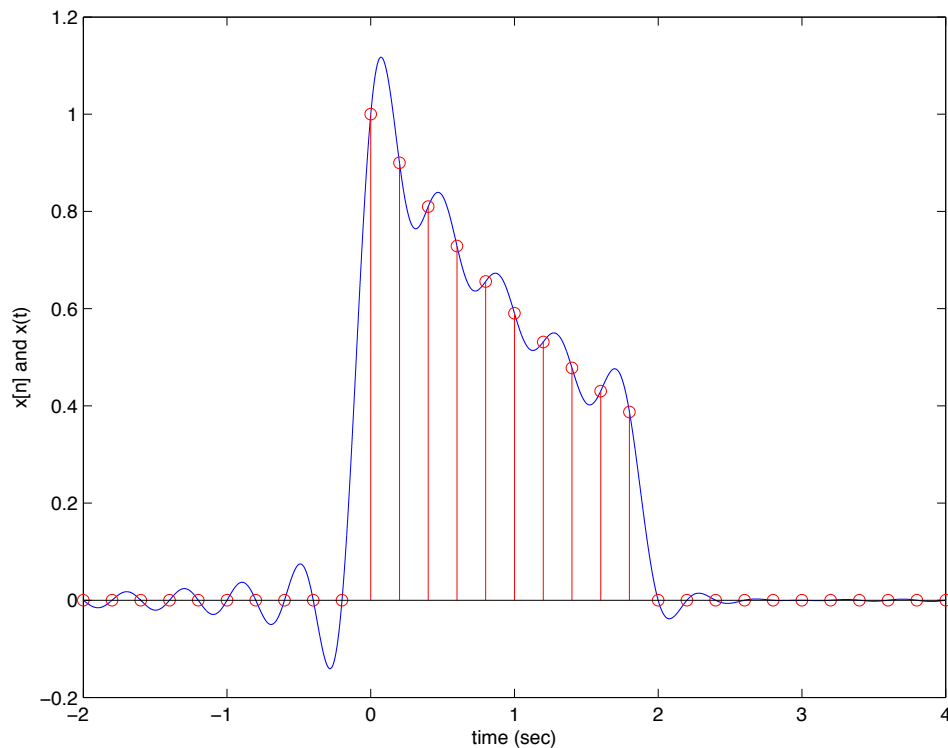
Note that  $x(t = 0.5) = x[n = 5]$  since this time falls directly on a sampling instant.

- (c) Now suppose the sampling period  $T = \frac{1}{5}$  seconds. Determine the value of  $x(t)$  at time  $t = 0.5$  seconds.

**Solution:** The ideal reconstruction formula states

$$\begin{aligned} x(t) &= \sum_{n=-\infty}^{\infty} x[n] \frac{\sin(\pi(t - nT)/T)}{\pi(t - nT)/T} \\ &= \sum_{n=0}^9 0.9^n \frac{\sin(5\pi(0.5 - n/5))}{5\pi(0.5 - n/5)} \\ &= \sum_{n=0}^9 0.9^n \frac{\sin(2.5\pi - n\pi)}{2.5\pi - n\pi} \\ &\approx 0.8316 \end{aligned}$$

where the final result was computed in Matlab. Note this time instant falls between two samples, so you have to compute the full sum.



```

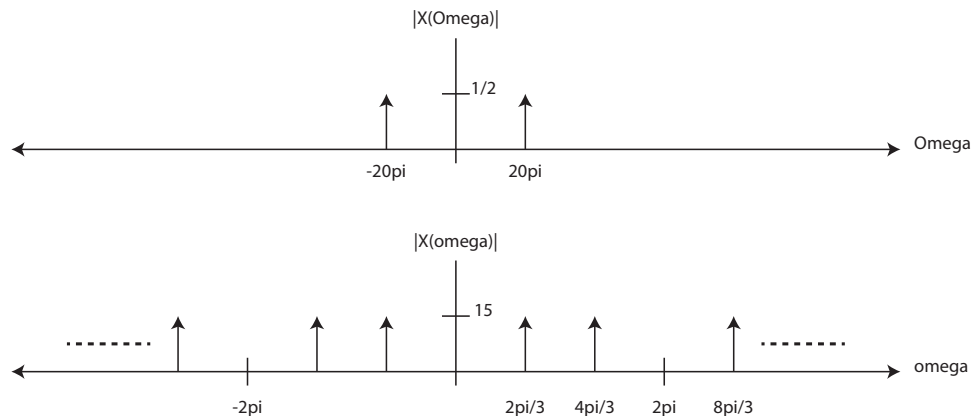
tt = -2:0.0001:4;
T = 1/5;
n = 0:9;
alpha = 0.9;
x = zeros(1,length(tt));
i1 = 0;
for t = tt,
    i1 = i1+1;
    x(i1) = sum((alpha.^n).*sin(pi*(t-n*T)/T)./(pi*(t-n*T)/T));
end
plot(tt,x);
hold on
stem(-2:T:4,[zeros(1,10) 0.9.^n zeros(1,11)],'r');
xlabel('time (sec)');
ylabel('x[n] and x(t)')

```

2. 4 points. Suppose you have a real-valued continuous-time signal  $x(t) = \cos(2\pi \cdot 10 \cdot t)$  and this signal is ideally sampled at frequency  $F_T = 30$  Hertz to generate a discrete-time signal  $x[n]$ .

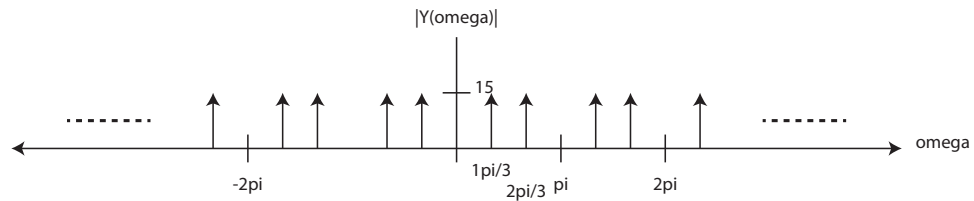
- (a) Sketch the magnitude of  $X(\Omega)$  and the magnitude of  $X(\omega)$ , explicitly showing any periodicity in the spectra. Is there aliasing?

**Solution:** There is no aliasing. The spectra are sketched below.



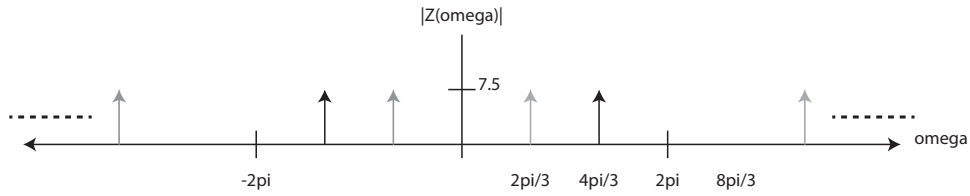
- (b) Now suppose  $x[n]$  is upsampled by a factor of two, resulting in  $y[n]$ . Sketch the magnitude of  $Y(\omega)$ , explicitly showing any periodicity in the spectrum.

**Solution:** There is still no aliasing here. The spectrum is sketched below. Note the additional tones that appear because of the up sampling. These tones could be attenuated/removed, if desired, with an interpolation filter.



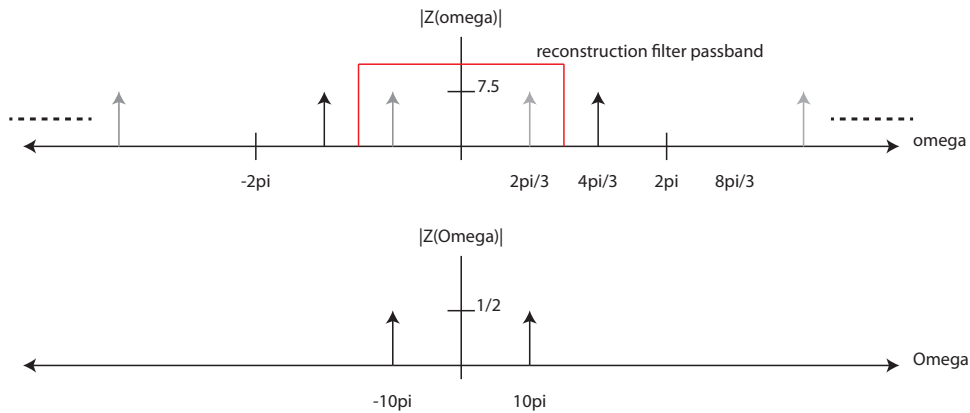
- (c) Now suppose  $x[n]$  is downsampled by a factor of two, resulting in  $z[n]$ . Sketch the magnitude of  $Z(\omega)$ , explicitly showing any periodicity in the spectrum.

**Solution:** Now there is aliasing. The spectrum is sketched below. The images at  $\pm 2\pi$  are shown in gray.



- (d) Now suppose  $z[n]$  is sent to an ideal reconstruction filter to generate  $z(t)$ . Note this ideal reconstruction filter will use a period of  $T = \frac{1}{15}$  seconds because the sampling rate of  $z[n]$  is 15 Hertz. Can you find a closed-form expression for  $z(t)$ ?

**Solution:** In this case, reconstruction is easily analyzed in the frequency domain. The ideal reconstruction filter will only pass normalized frequencies between  $-\pi$  and  $+\pi$ , hence we can sketch the spectra of  $Z(\omega)$  and  $Z(\Omega)$  as

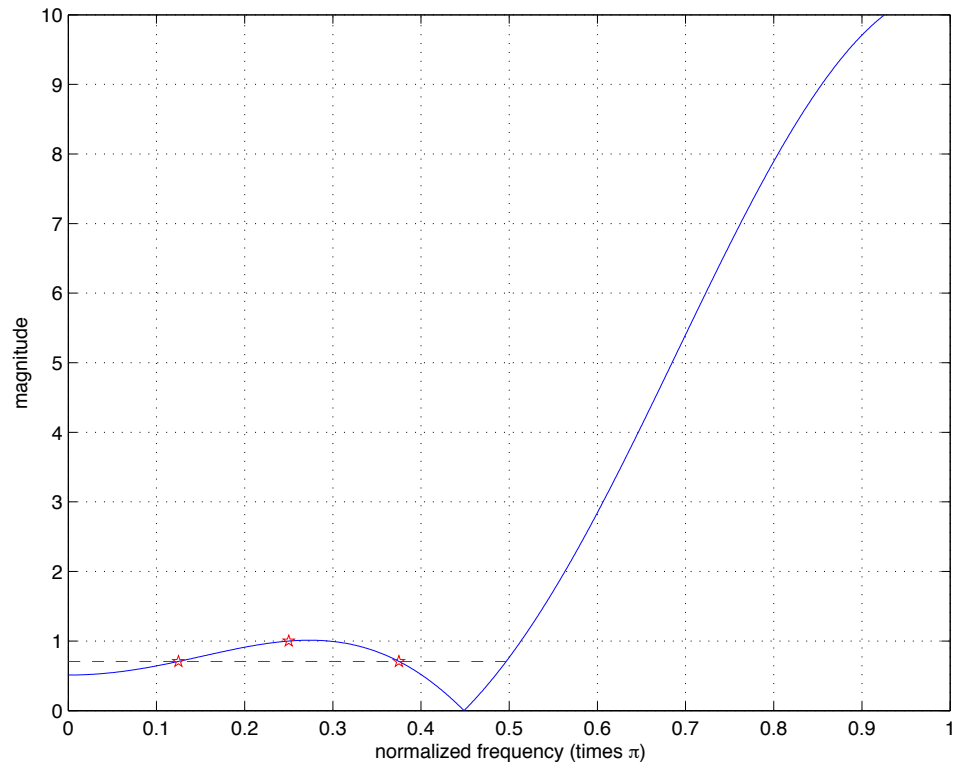


It is clear that  $z(t) = \cos(2\pi \cdot 5 \cdot t)$ . Aliasing in the downsampled signal caused the ideal reconstruction filter output to be different than the original time domain signal  $x(t)$ .

3. 4 points total. Suppose you wish to design a “bandpass” filter that has unity magnitude at  $\omega_1 = \frac{\pi}{4}$  and has magnitude  $\frac{1}{\sqrt{2}}$  at  $\omega_1 = \frac{\pi}{4} \pm \omega_0$ .

- (a) 2 points. Design a filter that meets these specifications when  $\omega_0 = \pi/8$ . Use Matlab to plot the magnitude response and confirm it agrees with the specifications. Is this a good bandpass filter? Why or why not?

**Solution:**



```
w1 = pi/4;
w0 = pi/8;
```

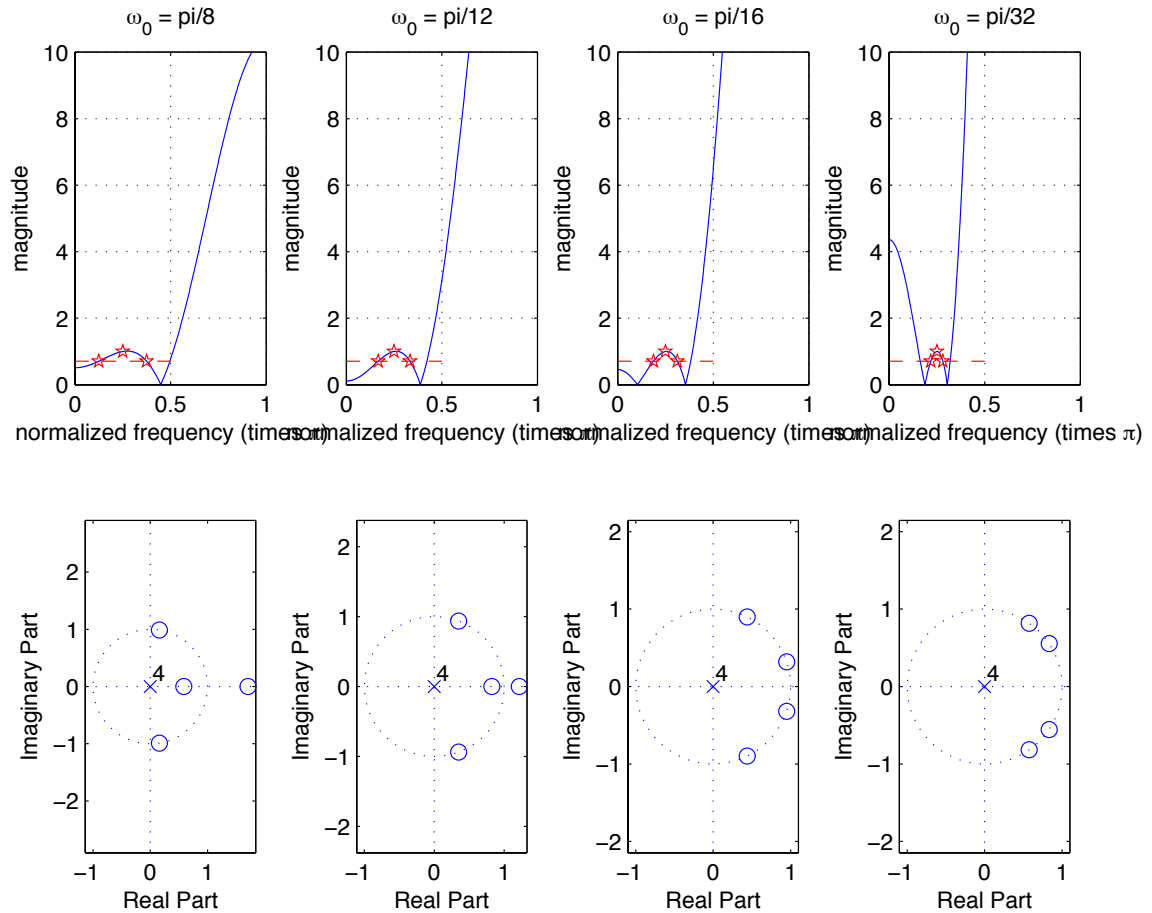
```
w = [w1-w0 w1 w1+w0]';
A = [2*cos(2*w) 2*cos(w) ones(3,1)];
b = [1/sqrt(2) 1 1/sqrt(2)]';
alpha = inv(A)*b;
```

```
h = [alpha ; alpha(end-1:-1:1)].';
[v,ww] = freqz(h,1,1024);
plot(ww/pi,abs(v),[0 0.5],[1/sqrt(2) 1/sqrt(2)],'r--',...
     w(1)/pi,1/sqrt(2),'rp',w(3)/pi,1/sqrt(2),'rp',w(2)/pi,1,'rp');
grid on
xlabel('normalized frequency (times \pi)');
ylabel('magnitude');
axis([0 1 0 10]);
```

This is not a very good bandpass filter. Even though it meets the specifications, this looks more like a highpass filter.

(b) 2 points. Discuss what happens as  $\omega_0$  gets small.

**Solution:** The following plot shows what happens when  $\omega_0 = \pi/8, \pi/12, \pi/16, \pi/32$ , including the magnitude response and the  $z$ -plane.



The magnitude response shows that the “passband” of our bandpass filter is becoming narrower, as we expected, but that the filter is becoming more like a bandstop filter as  $\omega_0$  gets small since the low and high frequencies are passed with higher gain than one. The  $z$ -plane plots are also interesting. We see the zeros moving closer to  $e^{\pm j\omega_1}$  as  $\omega_0$  gets small, but in order to keep the magnitude response of the filter unity at  $\omega_1$  the overall gain of the filter must increase. This explains why the high and low frequency gains of the filter increase as  $\omega_0$  gets small. Overall, this isn’t a very good way to design a narrowband bandpass filter.

4. 3 points. Suppose  $x[n]$  is a length- $N$  sequence and  $y[n]$  is a length- $2N$  sequence formed by repeating  $x[n]$  twice, i.e.

$$y[n] = \begin{cases} x[n] & n = 0, 1, \dots, N - 1 \\ x[n - N] & n = N, \dots, 2N - 1. \end{cases}$$

Let  $Y[k]$  be the  $2N$ -point DFT of  $y[n]$  for  $k = 0, \dots, 2N - 1$  and let  $Z[k] = Y[2k]$  for  $k = 0, 1, \dots, N - 1$ . Relate  $z[n] = \text{IDFT}\{Z[k]\}$  to  $x[n]$  for  $n = 0, \dots, N - 1$ .

**Solution:** Using what we covered in lecture about periodic extensions, we can say

$$Y[k] = \begin{cases} 2X[k/2] & k = 0, 2, 4, \dots, 2N - 2 \\ 0 & k = 1, 3, \dots, 2N - 1. \end{cases}$$

Now, since  $Z[k] = Y[2k]$  (downsampling in the frequency domain), then  $Z[k] = 2X[k]$  for  $k = 0, 1, \dots, N - 1$ , hence  $z[n] = 2x[n]$  for  $n = 0, 1, \dots, N - 1$ .

5. 4 points. Mitra 4.43. Suggested approach: Use  $z$ -domain analysis to find the zero-state response. To find the zero-input response, find the homogeneous solution and apply the initial conditions to solve for the unknown constants. Compute the total response as the sum of the zero-state response and the zero-input response. You can check your answer with Matlab.

**Solution:** Let's work on the zero-state response first. Given  $x[n] = 3^n \mu[n]$ , the transfer function is easily computed as

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 - 0.7z^{-1} - 0.02z^{-2}}$$

with ROC extending outward from the largest magnitude pole at  $z = 0.7275$  and  $X(z) = \frac{1}{1-3z^{-1}}$  with ROC  $|z| > 3$ . Hence

$$Y(z) = \frac{a}{1 - 0.7275z^{-1}} + \frac{b}{1 + 0.0275z^{-1}} + \frac{c}{1 - 3^{-1}}$$

and we need to calculate  $a$ ,  $b$ , and  $c$ . I get  $a = -0.3085$ ,  $b = 0.0003$ , and  $c = 1.3081$  using Matlab's `residuez` command. Hence, the zero-state response is

$$y_{zs}[n] = a(0.7275)^n \mu[n] + b(-0.0275)^n \mu[n] + c(3)^n \mu[n].$$

The zero-input response can be determined by writing the complementary solution

$$y_c[n] = \alpha_1(0.7275)^n + \alpha_2(-0.0275)^n$$

and solving for  $\alpha_1$  and  $\alpha_2$  based on the given initial conditions  $y[-1] = 3$  and  $y[-2] = 0$ . So we have two simultaneous equations

$$\begin{aligned} 3 &= \alpha_1(0.7275)^{-1} + \alpha_2(-0.0275)^{-1} \\ 0 &= \alpha_1(0.7275)^{-2} + \alpha_2(-0.0275)^{-2} \end{aligned}$$

and I get  $\alpha_1 = 2.1030$  and  $\alpha_2 = -0.0030$ . Hence, the zero-input response is

$$y_{zi}[n] = \alpha_1(0.7275)^n + \alpha_2(-0.0275)^n$$

for  $n \geq 0$ . Total response is then

$$\begin{aligned} y[n] &= y_{zs}[n] + y_{zi}[n] \\ &= \alpha_1(0.7275)^n \mu[n] + \alpha_2(-0.0275)^n \mu[n] + a(0.7275)^n \mu[n] + b(-0.0275)^n \mu[n] + c(3)^n \mu[n] \\ &= 1.7945(0.7275)^n \mu[n] - 0.0027(-0.0275)^n \mu[n] + 1.3081(3)^n \mu[n]. \end{aligned}$$

This can be confirmed in Matlab.

6. 3 points. Compute the impulse response of the system in Mitra 4.43.

**Solution:** We can use basically the same approach as before except  $x[n] = \delta[n]$  and the initial conditions are all zero since the impulse response implies that the system is relaxed. Since there is no zero-input response to worry about, we just have to find the inverse  $z$ -transform of the transfer function. This can be done via partial fraction expansion

$$H(z) = \frac{a}{1 - 0.7275z^{-1}} + \frac{b}{1 + 0.0275z^{-1}} = \frac{1}{1 - 0.7z^{-1} - 0.02z^{-2}}.$$

Solving for  $a$  and  $b$ , I get  $a = 0.9636$  and  $b = 0.0364$ . Hence the impulse response of this system is

$$h[n] = 0.9636(0.7275)^n \mu[n] + 0.0364(-0.0275)^n \mu[n].$$

which can also be confirmed in Matlab.



7. 4 points. Mitra 5.9.

$$(a) \quad Y_a[k] = \sum_{n=0}^{N-1} \alpha^n W_N^{kn} = \sum_{n=0}^{N-1} (\alpha W_N^k)^n = \frac{1 - \alpha^N W_N^{kN}}{1 - \alpha W_N^k} = \frac{1 - \alpha^N}{1 - \alpha W_N^k}.$$

$$(b) \quad \text{Note that } y_b[n] = \begin{cases} +4, & \text{for } n \text{ even,} \\ -2, & \text{for } n \text{ odd,} \end{cases} = 3(-1)^n + 1.$$

Hence we can use the result from Part (a) and write:

$$Y_b[k] = \sum_{n=0}^{N-1} [3(-1)^n + 1] W_N^{kn} = 3 \sum_{n=0}^{N-1} (-W_N^k)^n + \sum_{n=0}^{N-1} (W_N^k)^n.$$

Assume  $W_N^k \neq \pm 1$ . Then:

$$\begin{aligned} Y_b[k] &= 3 \frac{1 - (-W_N^k)^N}{1 - (-W_N^k)} + \frac{1 - (W_N^k)^N}{1 - (W_N^k)} = 3 \frac{(1 - (-W_N^k)^N)(1 - W_N^k)}{(1 - W_N^k)(1 + W_N^k)} + \frac{(1 - (W_N^k)^N)(1 + W_N^k)}{(1 - W_N^k)(1 + W_N^k)} \\ &= 3 \frac{(1 - (-1)^N e^{j2\pi k})(1 - W_N^k)}{(1 - W_N^k)(1 + W_N^k)} + \frac{(1 - e^{j2\pi k})(1 + W_N^k)}{(1 - W_N^k)(1 + W_N^k)} \\ &= \frac{(3 - 3W_N^k - 3(-1)^N e^{j2\pi k} + 3(-1)^N e^{j2\pi k} W_N^k) + (1 + W_N^k - e^{j2\pi k} - e^{j2\pi k} W_N^k)}{(1 - W_N^k)(1 + W_N^k)} \\ &= \frac{4 - 2W_N^k - 3(-1)^N e^{j2\pi k} + 3(-1)^N e^{j2\pi k} W_N^k - e^{j2\pi k} - e^{j2\pi k} W_N^k}{(1 - W_N^k)(1 + W_N^k)} \\ &= \frac{4 - 3(-1)^N e^{j2\pi k} - e^{j2\pi k} - W_N^k(2 - 3(-1)^N e^{j2\pi k} + e^{j2\pi k})}{(1 - W_N^k)(1 + W_N^k)}. \end{aligned}$$

Assume  $W_N^k = -1 \Leftrightarrow k = N/2$  (where  $N$  is necessarily even). Then:

$$Y_b[N/2] = 3 \sum_{n=0}^{N-1} (1)^n + \sum_{n=0}^{N-1} (-1)^n = 2N.$$

Now, suppose  $W_N^k = 1 \Leftrightarrow k = 0$ . Then,

$$Y_b[0] = 3 \sum_{n=0}^{N-1} (-1)^n + \sum_{n=0}^{N-1} (1)^n = 3 \frac{[1 - (-1)^N]}{1 - (-1)} + N = \frac{3}{2} [1 - (-1)^N] + N = \begin{cases} N, & \text{for } N \text{ even,} \\ 3 + N, & \text{for } N \text{ odd.} \end{cases}$$