

# ECE531 Lecture 10a: Maximum Likelihood Estimation

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# Introduction

- ▶ So far, we have two techniques for finding “good” estimators when the parameter is non-random:
  1. Rao-Blackwell-Lehmann-Sheffe technique for finding MVU estimators.
  2. “Guess and check”: use your intuition to guess at a good estimator and then compare variance to information inequality or CRLB
- ▶ Both techniques can fail or be difficult to use in some scenarios, e.g.
  - ▶ Can't find a complete sufficient statistic
  - ▶ Can't compute the conditional expectation in the RBLS theorem
  - ▶ Can't invert the Fisher information matrix
  - ▶ ...
- ▶ Today we will learn a third technique that can often help us find good estimators: the **maximum likelihood** criterion.

# The Maximum Likelihood Criterion

- ▶ Suppose for a moment that our parameter  $\Theta$  is random (like Bayesian estimation) and we have a prior on the unknown parameter  $\pi_{\Theta}(\theta)$ . The maximum a posteriori (MAP) estimator can be written as

$$\hat{\theta}_{\text{map}}(y) = \arg \max_{\theta \in \Lambda} p_{\Theta}(\theta | y) \stackrel{\text{Bayes}}{=} \arg \max_{\theta \in \Lambda} p_Y(y | \theta) \pi_{\Theta}(\theta)$$

- ▶ If you were unsure about this prior, you might assume a “least favorable prior”. Intuitively, what sort of prior would give the least information about the parameter?
- ▶ We could assume the prior is **uniformly distributed** over  $\Lambda$ , i.e.  $\pi_{\Theta}(\theta) \equiv \pi > 0$  for all  $\theta \in \Lambda$ . Then

$$\hat{\theta}_{\text{map}}(y) = \arg \max_{\theta \in \Lambda} p_Y(y; \theta) \pi = \arg \max_{\theta \in \Lambda} p_Y(y; \theta) = \hat{\theta}_{\text{ml}}(y)$$

finds the value of  $\theta$  that **makes the observation  $Y = y$  most likely.**

$\hat{\theta}_{\text{ml}}(y)$  is called the **maximum likelihood (ML)** estimator.

- ▶ Problem 1: If  $\Lambda$  is not a bounded set, e.g.  $\Lambda = \mathbb{R}$ , then  $\pi = 0$ . A uniform distribution on  $\mathbb{R}$  (or any unbounded  $\Lambda$ ) doesn't really make sense.

# The Maximum Likelihood Criterion

- ▶ Even though our development of the ML estimator is questionable, the criterion of finding the value of  $\theta$  that makes the observation  $Y = y$  most likely (assuming all parameter values are equally likely) is still interesting.
- ▶ Note that, since  $\ln$  is strictly monotonically increasing,

$$\hat{\theta}_{\text{ml}}(y) = \arg \max_{\theta \in \Lambda} p_Y(y; \theta) = \arg \max_{\theta \in \Lambda} \ln p_Y(y; \theta)$$

- ▶ Assuming that  $\ln p_Y(y; \theta)$  is differentiable, we can state a **necessary** (but not sufficient) condition for the ML estimator:

$$\left. \frac{\partial}{\partial \theta} \ln p_Y(y; \theta) \right|_{\theta = \hat{\theta}_{\text{ml}}(y)} = 0$$

where the partial derivative is taken to mean the gradient  $\nabla_{\theta}$  for multiparameter estimation problems.

- ▶ This expression is known as the **likelihood equation**.

# The Likelihood Equation's Relationship with the CRLB

- ▶ Recall from last week's lecture that we can attain the CRLB if and only if  $p_Y(y; \theta)$  is of the form

$$p_Y(y; \theta) = h(y) \exp \left\{ \int_a^\theta I(t) \left[ \hat{\theta}(y) - \theta \right] dt \right\}$$

$$\Leftrightarrow \ln p_Y(y; \theta) = \ln h(y) + \int_a^\theta I(t) \left[ \hat{\theta}(y) - \theta \right] dt$$

for all  $y \in \mathcal{Y}$ .

- ▶ When this condition holds, the likelihood equation becomes

$$\frac{\partial}{\partial \theta} \ln p_Y(y; \theta) \Big|_{\theta = \hat{\theta}_{\text{ml}}(y)} = I(\theta) \left[ \hat{\theta}(y) - \theta \right]_{\theta = \hat{\theta}_{\text{ml}}(y)} = 0$$

which, as long as  $I(\theta) > 0$ , has the unique solution  $\hat{\theta}_{\text{ml}}(y) = \hat{\theta}(y)$ .

- ▶ What does this mean? **If  $\hat{\theta}(y)$  attains the CRLB, it must be a solution to the likelihood equation.** The converse is not always true, however.

# Some Initial Properties of Maximum Likelihood Estimators

- ▶ If  $\hat{\theta}(y)$  attains the CRLB, it must be a solution to the likelihood equation.
  - ▶ In this case,  $\hat{\theta}_{\text{ml}}(y) = \hat{\theta}_{\text{mvu}}(y)$ .
- ▶ Solutions to the likelihood equation may not achieve the CRLB.
  - ▶ In this case, it may be possible to find other unbiased estimators with lower variance than the ML estimator.

# Example: Estimating a Constant in White Gaussian Noise

Suppose we have random observations given by

$$Y_k = \theta + W_k \quad k = 0, \dots, n-1$$

where  $W_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ . The unknown parameter  $\theta$  is non-random and can take on any value on the real line (we have no prior pdf).

Let's set up the likelihood equation  $\left. \frac{\partial}{\partial \theta} \ln p_Y(y; \theta) \right|_{\theta = \hat{\theta}_{\text{ml}}(y)} = 0 \dots$

We can write

$$\frac{\partial}{\partial \theta} \ln \frac{1}{(2\pi\sigma^2)^{n/2}} \exp \left\{ \frac{-\sum_{k=0}^{n-1} (y_k - \theta)^2}{2\sigma^2} \right\} \Big|_{\theta = \hat{\theta}_{\text{ml}}} = \frac{1}{\sigma^2} \sum_{k=0}^{n-1} (y_k - \hat{\theta}_{\text{ml}}) = 0$$

hence

$$\hat{\theta}_{\text{ml}}(y) = \frac{1}{n} \sum_{k=0}^{n-1} y_k = \bar{y}.$$

This solution is unique. You can also easily confirm that it maximizes  $\ln p_Y(y; \theta)$ .

# Example: Est. the Parameter of an Exponential Distrib.

Suppose we have random observations given by  $Y_k \stackrel{\text{i.i.d.}}{\sim} \theta e^{-\theta y_k}$  for  $k = 0, \dots, n-1$  and  $y_k \geq 0$ . The unknown parameter  $\theta > 0$  and we have no prior pdf.

Let's set up the likelihood equation  $\left. \frac{\partial}{\partial \theta} \ln p_Y(y; \theta) \right|_{\theta = \hat{\theta}_{\text{ml}}(y)} = 0 \dots$

Since  $p_Y(y; \theta) = \prod_k p_{Y_k}(y_k; \theta) = \theta^n \exp\{-\theta \sum_k y_k\}$ , we can write

$$\begin{aligned} \left. \frac{\partial}{\partial \theta} \ln [\theta^n \exp\{-n\theta \bar{y}\}] \right|_{\theta = \hat{\theta}_{\text{ml}}} &= \left. \frac{\partial}{\partial \theta} (n \ln \theta - n\theta \bar{y}) \right|_{\theta = \hat{\theta}_{\text{ml}}} \\ &= \frac{n}{\hat{\theta}_{\text{ml}}(y)} - n\bar{y} = 0 \end{aligned}$$

which has the unique solution  $\hat{\theta}_{\text{ml}}(y) = 1/\bar{y}$ . You can easily confirm that this solution is a maximum of  $p_Y(y; \theta)$  since  $\frac{\partial^2}{\partial \theta^2} \ln p_Y(y; \theta) = \frac{-n}{\theta^2} < 0$ .



# Example: Est. the Parameter of an Exponential Distrib.

Assuming  $n \geq 2$ , the mean of the ML estimator can be computed as

$$E_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = \frac{n}{n-1} \theta$$

Note that  $\hat{\theta}_{\text{ml}}(y)$  is biased for finite  $n$  but it is **asymptotically unbiased** in the sense that  $\lim_{n \rightarrow \infty} E_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = \theta$ . Assuming  $n \geq 3$ , the variance of the ML estimator can be computed as

$$\text{var}_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = \frac{n^2 \theta^2}{(n-1)^2 (n-2)} > \frac{\theta^2}{n} = I^{-1}(\theta)$$

where  $I(\theta)$  is the Fisher information for this estimation problem.

- ▶ Since  $\frac{\partial}{\partial \theta} \ln p_Y(y; \theta)$  is not of the form  $k(\theta) \left[ \hat{\theta}_{\text{ml}}(y) - f(\theta) \right]$ , we know that the information inequality can not be attained here.
- ▶ Nevertheless,  $\hat{\theta}_{\text{ml}}(y)$  is **asymptotically efficient** in the sense that  $\lim_{n \rightarrow \infty} \text{var}_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = I^{-1}(\theta)$ .

# Example: Est. the Parameter of an Exponential Distrib.

It can be shown using the RBLs theorem and our theorem about complete sufficient statistics for exponential density families that

$$\hat{\theta}_{\text{mvu}}(y) = \left( \frac{1}{n-1} \sum_{k=0}^{n-1} y_k \right)^{-1} = \frac{n-1}{n} \hat{\theta}_{\text{ml}}(y).$$

Assuming  $n \geq 3$ , the variance of the MVU estimator is then

$$\text{var}_{\theta} \left\{ \hat{\theta}_{\text{mvu}}(Y) \right\} = \frac{\theta^2}{n-2} > \frac{\theta^2}{n} = I^{-1}(\theta).$$

Which is better,  $\hat{\theta}_{\text{ml}}(y)$  or  $\hat{\theta}_{\text{mvu}}(y)$ ?

# Which is Better, MVU or ML?

To answer this question, you have to return to what got us here: the **squared error** cost function.

$$\begin{aligned} E_{\theta} \left\{ (\hat{\theta}_{\text{ml}}(Y) - \theta)^2 \right\} &= \text{var}_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} + \left( \frac{\theta}{n-1} \right)^2 = \frac{n+2}{n-1} \cdot \frac{\theta^2}{n-2} \\ &> \frac{\theta^2}{n-2} = \text{var}_{\theta} \left\{ \hat{\theta}_{\text{mvu}}(Y) \right\}. \end{aligned}$$

The MVU estimator is preferable to the ML estimator for finite  $n$ . Asymptotically, however, their squared error performance is equivalent.

## Example: Estimating a The Mean and Variance of WGN

Suppose we have random observations given by  $Y_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, \sigma^2)$  for  $k = 0, \dots, n - 1$ . The unknown vector parameter  $\theta = [\mu, \sigma^2]$  where  $\mu \in \mathbb{R}$  and  $\sigma^2 > 0$ . The joint density is given as

$$p_Y(y; \theta) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp \left\{ \frac{-\sum_{k=0}^{n-1} (y_k - \mu)^2}{2\sigma^2} \right\}$$

How should we approach this joint maximization problem? In general, we would compute the gradient  $\nabla_{\theta} \ln p_Y(y; \theta) \Big|_{\theta = \hat{\theta}_{\text{ml}}(y)}$ , set the result equal to zero, and then try to solve the simultaneous equations (also using the Hessian to check that we did indeed find a maximum)...

Or we could recognize that finding the value of  $\mu$  that maximizes  $p_Y(y; \theta)$  does not depend on  $\sigma^2$ ...

# Example: Estimating a The Mean and Variance of WGN

We already know  $\hat{\mu}_{\text{ml}}(y)$  for estimating  $\mu$ :

$$\hat{\mu}_{\text{ml}}(y) = \bar{y} \quad (\text{same as MVU estimator}).$$

So now we just need to solve

$$\hat{\sigma}_{\text{ml}}^2 = \arg \max_{a>0} \left( \ln \left\{ \frac{1}{(2\pi a)^{n/2}} \exp \left\{ \frac{-\sum_{k=0}^{n-1} (y_k - \bar{y})^2}{2a} \right\} \right\} \right)$$

Skipping the details (standard calculus, see example IV.D.2 in your textbook), it can be shown that

$$\hat{\sigma}_{\text{ml}}^2 = \frac{1}{n} \sum_{k=0}^{n-1} (y_k - \bar{y})^2$$

# Example: Estimating a The Mean and Variance of WGN

Is  $\hat{\sigma}_{ml}^2$  biased in this case?

$$\begin{aligned}
 E_{\theta} \{ \hat{\sigma}_{ml}^2(Y) \} &= \frac{1}{n} \sum_{k=0}^{n-1} E_{\theta} [(Y_k - \mu)^2 - 2(Y_k - \mu)(\bar{Y} - \mu) + (\bar{Y} - \mu)^2] \\
 &= \frac{1}{n} \sum_{k=0}^{n-1} \sigma^2 - \frac{2\sigma^2}{n} + \frac{\sigma^2}{n} \\
 &= \frac{n-1}{n} \sigma^2
 \end{aligned}$$

Yes,  $\hat{\sigma}_{ml}^2$  is biased but it is asymptotically unbiased.

The steps in the previous analysis can be followed to show that  $\hat{\sigma}_{ml}^2$  is unbiased if  $\mu$  is known. The unknown mean, even though we have an unbiased efficient estimator of it, causes  $\hat{\sigma}_{ml}^2(y)$  to be biased here.

# Example: Estimating a The Mean and Variance of WGN

It can also be shown that

$$\text{var} \{ \hat{\sigma}_{\text{ml}}^2(Y) \} = \frac{2(n-1)\sigma^4}{n^2} < \frac{2\sigma^4}{n-1} = \text{var} \{ \hat{\sigma}_{\text{mvu}}^2(Y) \}$$

Which is better,  $\hat{\sigma}_{\text{ml}}^2(y)$  or  $\hat{\sigma}_{\text{mvu}}^2(y)$ ? To answer this, let's compute the mean squared error (MSE) of the ML estimator for  $\sigma^2$ :

$$\begin{aligned} \mathbb{E}_{\theta} \{ (\hat{\sigma}_{\text{ml}}^2(Y) - \sigma^2)^2 \} &= \text{var}_{\theta} \{ \hat{\sigma}_{\text{ml}}^2(Y) \} + (\mathbb{E}_{\theta} \{ \hat{\sigma}_{\text{ml}}^2(Y) \} - \sigma^2)^2 \\ &= \frac{2(n-1)\sigma^4}{n^2} + \left( \frac{n-1}{n}\sigma^2 - \sigma^2 \right)^2 \\ &= \frac{(2n-1)\sigma^4}{n^2} \\ &< \frac{2\sigma^4}{n-1} = \mathbb{E}_{\theta} \{ (\hat{\sigma}_{\text{mvu}}^2(Y) - \sigma^2)^2 \} \end{aligned}$$

Hence the ML estimator has uniformly lower mean squared error (MSE) performance than the MVU estimator. **The increase in MSE due to the bias is more than offset by the decreased variance of the ML estimator.**

# More Properties of ML Estimators

From our examples, we can say that

- ▶ Maximum likelihood estimators may be biased.
- ▶ A biased ML estimator may, in some cases, outperform a MVU estimator in terms of overall mean squared error.
- ▶ It seems that ML estimators are often asymptotically unbiased:

$$\lim_{n \rightarrow \infty} E_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = \theta$$

Is this always true?

- ▶ It seems that ML estimators are often asymptotically efficient:

$$\lim_{n \rightarrow \infty} \text{var}_{\theta} \left\{ \hat{\theta}_{\text{ml}}(Y) \right\} = I^{-1}(\theta)$$

Is this always true?



# Consistency of ML Estimators For i.i.d. Observations

Suppose that we have i.i.d. observations with marginal distribution  $Y_k \stackrel{\text{i.i.d.}}{\sim} p_Z(z; \theta)$  and define

$$\psi(z; \theta') := \left. \frac{\partial}{\partial \theta} \ln p_Z(z; \theta) \right|_{\theta=\theta'}$$

$$J(\theta; \theta') := E_{\theta} \{ \psi(Y_k; \theta') \} = \int_{\mathcal{Z}} \psi(z; \theta') p_Z(z; \theta) dz$$

where  $\mathcal{Z}$  is the support of the pdf of a single observation  $p_Z(z; \theta)$ .

## Theorem

*If all of the following (sufficient but not necessary) conditions hold*

- 1.  $J(\theta; \theta')$  is a continuous function of  $\theta'$  and has a unique root  $\theta' = \theta$  at which point  $J$  changes sign,*
- 2.  $\psi(Y_k; \theta')$  is a continuous function of  $\theta'$  (almost surely), and*
- 3. For each  $n$ ,  $\frac{1}{n} \sum_{k=0}^{n-1} \psi(Y_k; \theta')$  has a unique root  $\hat{\theta}_n$  (almost surely),*

*then  $\hat{\theta}_n \xrightarrow{i.p.} \theta$ , where  $\xrightarrow{i.p.}$  means convergence in probability.*

# Consistency of ML Estimators For i.i.d. Observations

Convergence in probability means that

$$\lim_{n \rightarrow \infty} \text{Prob}_{\theta} \left[ \left| \hat{\theta}_n(Y) - \theta \right| > \epsilon \right] = 0 \text{ for all } \epsilon > 0$$

**Example:** Estimating a constant in white Gaussian noise:  $Y_k = \theta + W_k$  for  $k = 0, \dots, n-1$  with  $W_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ . For finite  $n$ , we know the estimator  $\hat{\theta}_n(y) = \bar{y} \sim \mathcal{N}(\theta, \sigma^2/n)$ . Hence

$$\text{Prob}_{\theta} \left[ \left| \hat{\theta}_n(Y) - \theta \right| > \epsilon \right] = 2Q \left( \frac{\sqrt{n}\epsilon}{\sigma} \right)$$

and

$$\lim_{n \rightarrow \infty} 2Q \left( \frac{\sqrt{n}\epsilon}{\sigma} \right) = 0$$

for any  $\epsilon > 0$ . So this estimator (ML=MVU here) is consistent.

# Consistency of ML Estimators: Intuition

Setting likelihood equation equal to zero for i.i.d. observations:

$$\frac{\partial}{\partial \theta} \ln p_Y(y; \theta) \Big|_{\theta=\theta'} = \sum_{k=0}^{n-1} \psi(y_k; \theta') = 0 \quad (1)$$

The **weak law of large numbers** tells us that

$$\frac{1}{n} \sum_{k=0}^{n-1} \psi(Y_k; \theta') \xrightarrow{\text{i.p.}} \mathbb{E}_{\theta} \{ \psi(Y_1; \theta') \} = J(\theta; \theta')$$

Hence, solving (1) in the limit as  $n \rightarrow \infty$  is equivalent to finding  $\theta'$  such that  $J(\theta; \theta') = 0$ . Under our usual regularity conditions, it is easy to show that  $J(\theta; \theta')$  will always have a root at  $\theta' = \theta$ .

$$\begin{aligned} J(\theta; \theta') \Big|_{\theta'=\theta} &= \int_{\mathcal{Z}} \frac{\partial}{\partial \theta} \ln p_Z(z; \theta) p_Z(z; \theta) dz \\ &= \int_{\mathcal{Z}} \frac{\frac{\partial}{\partial \theta} p_Z(z; \theta)}{p_Z(z; \theta)} p_Z(z; \theta) dz = \frac{\partial}{\partial \theta} \int_{\mathcal{Z}} p_Z(z; \theta) dz = 0 \end{aligned}$$

# Asymptotic Unbiasedness of ML Estimators

An estimator is asymptotically unbiased if

$$\lim_{n \rightarrow \infty} E_{\theta} \left\{ \hat{\theta}_{\text{ml},n}(Y) \right\} = \theta$$

Asymptotically unbiasedness requires **convergence in mean**. We've already seen several examples of ML estimators that are asymptotically unbiased.

Consistency implies that

$$E_{\theta} \left\{ \lim_{n \rightarrow \infty} \hat{\theta}_{\text{ml},n}(Y) \right\} = \theta$$

This is **convergence in probability**. Does consistency imply asymptotic unbiasedness? Only when the limit and expectation can be exchanged.

- ▶ In most cases, this exchange is valid (see email sent last Friday).
- ▶ If you want to know more precisely the conditions under which this exchange is valid, you need to learn about “dominated convergence” (a course in Analysis will cover this).

# Asymptotic Normality of ML Estimators

Main idea: For i.i.d. observations each distributed as  $p_Z(z; \theta)$  and under regularity conditions similar to those you've seen before,

$$\sqrt{n}(\hat{\theta}_{\text{ml},n}(Y) - \theta) \xrightarrow{d} \mathcal{N}\left(0, \frac{1}{i(\theta)}\right)$$

where  $\xrightarrow{d}$  means convergence in distribution and

$$i(\theta) := \mathbb{E}_\theta \left\{ \left[ \frac{\partial}{\partial \theta} \ln p_Z(Z; \theta) \right]^2 \right\}$$

is the Fisher information of a single observation  $Y_k$  about the parameter  $\theta$ .

**See Proposition IV.D.2 in your textbook for the details.**

# Asymptotic Normality of ML Estimators

- ▶ The asymptotic normality of ML estimators is very important.
- ▶ For similar reasons that convergence in probability is not sufficient to imply asymptotic unbiasedness, convergence in distribution is also not sufficient to imply that

$$E_{\theta}[\sqrt{n}(\hat{\theta}_n(Y) - \theta)] \rightarrow 0 \text{ (asymptotic unbiasedness)}$$

or

$$\text{var}_{\theta}[\sqrt{n}(\hat{\theta}_n(Y) - \theta)] \rightarrow \frac{1}{i(\theta)} \text{ (asymptotic efficiency).}$$

- ▶ Nevertheless, as our examples showed, ML estimators are often both asymptotically unbiased and asymptotically efficient.
- ▶ When an estimator is asymptotically unbiased and asymptotically efficient, it is asymptotically MVU.

# Conclusions

- ▶ Even though we started out with some questionable assumptions to specify the ML estimator, we found that that ML estimators can have nice properties:
  - ▶ If an estimator achieves the CRLB, then it must be a solution to the likelihood equation. Note that the converse is not always true.
  - ▶ For i.i.d. observations, ML estimators are guaranteed to be **consistent** (within regularity).
  - ▶ For i.i.d. observations, ML estimators are **asymptotically Gaussian** (within regularity).
  - ▶ For i.i.d. observations, ML estimators are **often asymptotically unbiased** and **asymptotically efficient**.
- ▶ Unlike MVU estimators, ML estimators may be biased.
- ▶ It is customary in many problems to assume sufficiently large  $n$  such that the asymptotic properties hold, at least approximately.
- ▶ Extensions to vector parameters can be found in the Poor textbook.