

ECE 531

Midterm exam Solution

Spring 2009

Problem 1 :

a) This is a simple binary HT problem.

b) states : $x_0 = \text{"good"}$
 $x_1 = \text{"defective"}$

observations : $y_0 = \text{"green"}$
 $y_1 = \text{"yellow"}$
 $y_2 = \text{"red"}$

conditional distributions :

$$P_0(y) = \begin{cases} P & y = y_0 \\ 1-P & y = y_1 \\ 0 & y = y_2 \end{cases}$$

$$P_1(y) = \begin{cases} 0 & y = y_0 \\ 1-P & y = y_1 \\ P & y = y_2 \end{cases}$$

hypotheses : $H_0 : X = x_0$ (good widget)

$H_1 : X = x_1$ (defective widget)

c) There are 8 deterministic decision rules

$$D = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \text{ always decide } H_0$$

⋮

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \text{ always decide } H_1$$

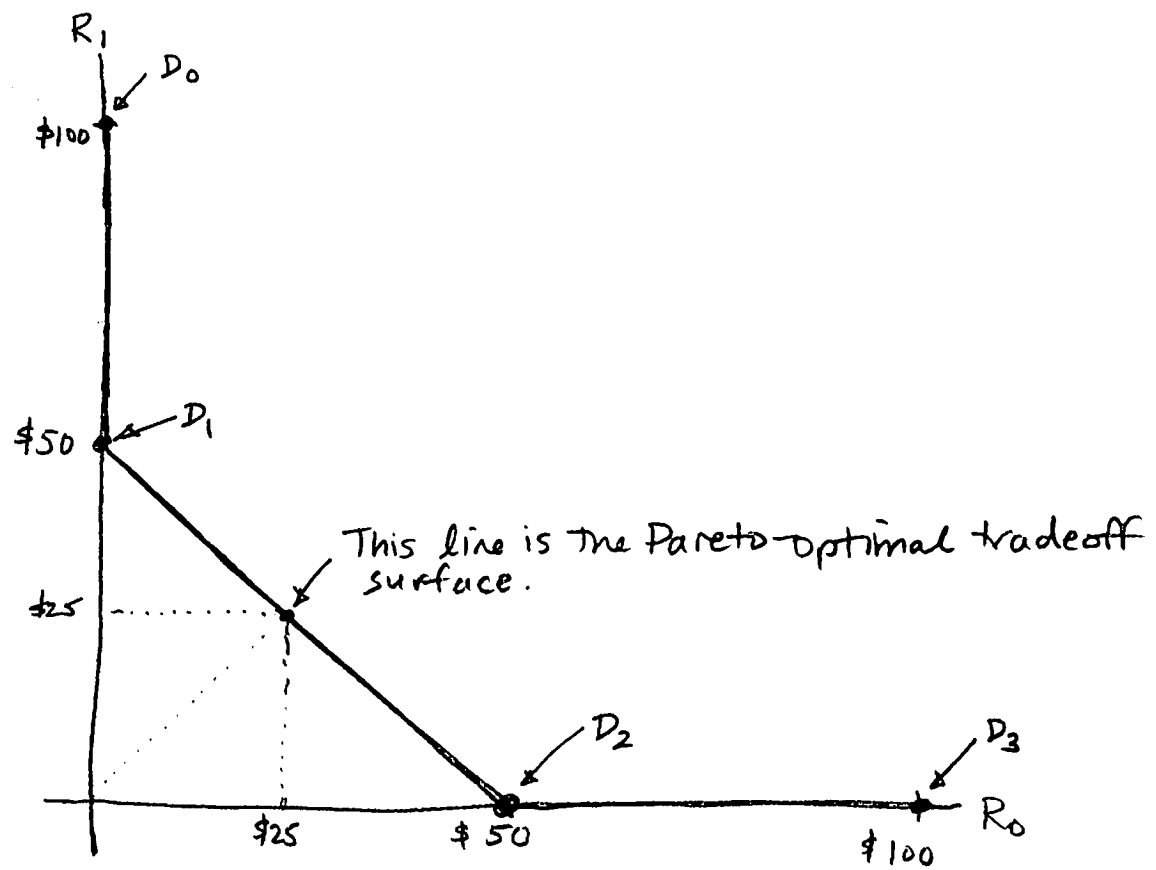
d) We can save some time here by realizing that there are only four good deterministic decision rules:

$D_0 = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ always decide H_0

$D_1 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ decide H_1 if widget tester shows "red" otherwise decide H_0 .

$D_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$ decide H_0 if widget tester shows "green" otherwise decide H_1 .

$D_3 = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix}$ always decide H_1 .



$R_0(D_1) =$ expected cost of deciding H_1 when true state is $x_0 = 0$

$R_1(D_1) =$ expected cost of deciding H_0 when true state is $x_1 = (1-p) \cdot 100 = \50

Similarly $R_0(D_2) = \$50$ and $R_1(D_2) = 0$

e) From the plot in part (d), we note that a randomized decision rule can achieve the risk trade off $R_0 = R_1 = \$25$.

This randomized decision rule is

$$D^* = \frac{1}{2} D_1 + \frac{1}{2} D_2 = \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 1 \end{bmatrix}$$

check

$$R_0(D^*) = \frac{1}{2} (1-p) \cdot \$100 = \$25$$

$$R_1(D^*) = \frac{1}{2} (1-p) \cdot \$100 = \$25. \quad \checkmark$$

This is a minimax decision rule (equal risks).

b) Minimax - try the equalizer rule

(6)

$$R_0(\delta^{B\pi}) = P(y^2 \geq \frac{\theta}{3} [\ln(\frac{\pi_0}{\pi_1}) - \ln(2)] \mid X = x_0)$$

$$= 2Q\left(\sqrt{\frac{\theta}{3} [\ln(\frac{\pi_0}{\pi_1}) + \ln(2)]}\right)$$



$$R_1(\delta^{B\pi}) = P(y^2 < \frac{\theta}{3} [\ln(\frac{\pi_0}{\pi_1}) - \ln(2)] \mid X = x_1)$$

$$= 1 - 2Q\left(\frac{\sqrt{\frac{\theta}{3} [\ln(\frac{\pi_0}{\pi_1}) + \ln(2)]}}{2}\right)$$



Set $R_0(\delta^{B\pi}) = R_1(\delta^{B\pi})$

$2Q(x) = 1 - 2Q(\frac{x}{2})$ use approximation

$$1 - \frac{2x}{\sqrt{2\pi}} = 1 - (1 - \frac{x}{\sqrt{2\pi}}) \Rightarrow \frac{3x}{\sqrt{2\pi}} = 1 \quad x = \frac{\sqrt{2\pi}}{3} \approx 0.836$$

hence $\sqrt{\frac{\theta}{3} [\ln(\frac{\pi_0}{\pi_1}) + \ln(2)]} = 0.836$

$$\ln(\frac{\pi_0}{\pi_1}) + \ln(2) = 0.2618$$

$$\frac{\pi_0}{\pi_1} = 0.6496$$

hence $\left. \begin{matrix} \pi_0^* = 0.3938 \\ \pi_1^* = 0.6062 \end{matrix} \right\}$ least favorable prior

Hence $\delta^{mm} = \delta^{B\pi}$ for $\pi = [0.3938, 0.6062]$

$$\delta^{mm} = \begin{cases} 1 & y^2 \geq .698 \\ 0 & y^2 < .698 \end{cases}$$

c) Neyman-Pearson

We need to find $v > 0$ such that $P(y^2 \geq v^2 \mid X = x_0) = \alpha$.
 Since we are dealing with smooth distributions here, we don't need to worry about randomization.

$$P(y^2 \geq v^2 \mid X = x_0) = 2Q(v) = \alpha$$

$$v = Q^{-1}\left(\frac{\alpha}{2}\right)$$

Hence
$$P^{N-P} = \begin{cases} 1 & y^2 \geq (Q^{-1}(\frac{\alpha}{2}))^2 \\ 0 & y^2 < (Q^{-1}(\frac{\alpha}{2}))^2 \end{cases}$$

N-P sized α

3. a) Let's check to see if a UMP decision rule exists

Let $\lambda = a > 1$ (fixed) \Rightarrow simple binary HT problem

$$L_a(y) = \frac{P_{\lambda=a}(y)}{P_0(y)} = \frac{a e^{-ay}}{e^{-y}} = a e^{-(a-1)y}$$

$$\ln(L_a(y)) = \ln(a) - (a-1)y \stackrel{\geq}{\leq} v$$

Hence, the optimum decision rule for this simple binary problem is

$$p^{N-P} = \begin{cases} 1 & y \leq \frac{v - \ln(a)}{a-1} \\ 0 & y > \frac{v - \ln(a)}{a-1} \end{cases}$$

$$P_{fp} = P\left(y \leq \frac{v - \ln(a)}{a-1} \mid X = x_0\right) = \alpha$$

$$= \int_0^{\frac{v - \ln(a)}{a-1}} e^{-y} dy = -e^{-y} \Big|_0^{\frac{v - \ln(a)}{a-1}} = 1 - e^{-\left(\frac{v - \ln(a)}{a-1}\right)} = \alpha$$

$$-\ln(1 - \alpha) = \frac{v - \ln(a)}{a-1}$$

Hence the critical region is simply defined by $\ln\left(\frac{1}{1-\alpha}\right)$

Not a function of the parameter a .

Hence the UMP decision rule is simply

$$p^{N-P} = \begin{cases} 1 & y \leq \ln\left(\frac{1}{1-\alpha}\right) \\ 0 & y > \ln\left(\frac{1}{1-\alpha}\right) \end{cases}$$

b) power function : $P\left(y \leq \ln\left(\frac{1}{1-\alpha}\right) \mid X = x_1\right)$

$$= \int_0^{\ln\left(\frac{1}{1-\alpha}\right)} \lambda e^{-\lambda y} dy = 1 - (1-\alpha)^\lambda$$

