

# ECE531 Homework Assignment Number 8

## Solution

Make sure your reasoning and work are clear to receive full credit for each problem.

1. 4 points. The equality condition on the Cauchy-Schwarz inequality implies that the information bound is attained if and only if

$$\frac{\partial}{\partial \theta} \ln p_Y(y; \theta) = k(\theta) \left[ \hat{\theta}(y) - \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\} \right]$$

almost surely for some  $k(\theta)$ . Assuming all of the regularity conditions hold, show that

$$k(\theta) = \frac{I(\theta)}{\frac{\partial}{\partial \theta} \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\}}.$$

What is  $k(\theta)$  when we have an unbiased estimator?

**Solution:** From slide 12 of the lecture notes, when Cauchy-Schwarz inequality becomes equality we have

$$\begin{aligned} \left[ \frac{\partial}{\partial \theta} \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\} \right]^2 &= \mathbb{E}_\theta \left\{ \left[ \hat{\theta}(Y) - \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\} \right]^2 \right\} \cdot I(\theta) \\ &= \mathbb{E}_\theta \left\{ \left[ \frac{\frac{\partial}{\partial \theta} \ln p_Y(Y; \theta)}{k(\theta)} \right]^2 \right\} \cdot I(\theta) \\ &= \frac{I(\theta)}{k^2(\theta)} \cdot I(\theta) \end{aligned}$$

Hence

$$k(\theta) = \pm \frac{I(\theta)}{\frac{\partial}{\partial \theta} \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\}}.$$

is a constant (in  $y$ ) that achieves the information bound. To show that the negative option can be eliminated, consider a scalar observation drawn from the family of densities

$$p_Y(y; \theta) = \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{(y - \theta)^2}{2} \right\}.$$

We know that the MVU estimator in this case is simply  $\hat{\theta}(y) = y$  and that this MVU estimator achieves the CRLB of  $1/I(\theta) = 1$ . It is not difficult to compute  $\frac{\partial}{\partial \theta} \ln p_Y(y; \theta) = y - \theta$ . Hence, we have

$$\begin{aligned} \frac{\partial}{\partial \theta} \ln p_Y(y; \theta) &= k(\theta) \left[ \hat{\theta}(y) - \mathbb{E}_\theta \left\{ \hat{\theta}(Y) \right\} \right] \\ y - \theta &= k(\theta)(y - \theta) \end{aligned}$$

which has only one solution:  $k(\theta) = 1$ . Hence, in general, the unique  $k(\theta)$  that achieves the bound is

$$k(\theta) = \frac{I(\theta)}{\frac{\partial}{\partial \theta} \mathbb{E}_\theta \{\hat{\theta}(Y)\}}.$$

When we have an unbiased estimator,  $\mathbb{E}_\theta \{\hat{\theta}(Y)\} = \theta$  and  $k(\theta) = I(\theta)$ .

2. 4 points. Poor textbook Chapter IV, Problem 13 (c).

**Solution:**

$$\frac{\partial^2}{\partial \theta^2} \log p_Y(Y; \theta) = -\frac{T(Y)}{\theta^2} - \frac{n - T(Y)}{(1 - \theta)^2},$$

from which

$$I(\theta) = \frac{n}{\theta} + \frac{n}{1 - \theta} = \frac{n}{\theta(1 - \theta)}.$$

The CRLB for an unbiased estimator is thus

$$\text{CRLB} = \frac{1}{I(\theta)} = \frac{\theta(1 - \theta)}{n}$$

3. 4 points. Poor textbook Chapter IV, Problem 20 (b). Hint: For a Gaussian random variable  $Y$ , we know  $\frac{\mathbb{E}\{Y^4\}}{\mathbb{E}^2\{Y^2\}} = 3$ .

**Solution:** First compute the Fisher information:

$$\begin{aligned} I(\theta) &= -\mathbb{E}_\theta \left\{ \frac{\partial^2}{\partial \theta^2} \log p_Y(y; \theta) \right\} = \sum_{k=1}^n \left\{ \frac{s_k^4 \mathbb{E}_\theta \{Y_k^2\}}{(1 + \theta s_k^2)^3} - \frac{s_k^4}{2(1 + \theta s_k^2)^2} \right\} \\ &= \frac{1}{2} \sum_{k=1}^n \frac{s_k^4}{(1 + \theta s_k^2)^2}. \end{aligned}$$

So the CRLB is

$$\frac{2}{\sum_{k=1}^n \frac{s_k^4}{(1 + \theta s_k^2)^2}}.$$

4. 4 points. Poor textbook Chapter IV, Problem 21 (a), (b), (c), and (e).

**Solution:**

(a) First we write out the pdf's of our two observations:

$$p_{Y_i}(y_i; \lambda) = \begin{cases} \frac{\lambda^{y_i} e^{-\lambda}}{y_i!} & y_i \in \{0, 1, 2, 3, \dots\} \\ 0 & \text{else} \end{cases} \quad \text{for } i = 1, 2$$

The two observations are independent and thus we can write the pdf of the vector observation  $y$  as

$$p_Y(y; \lambda) = p(y_1; \lambda)p(y_2; \lambda) = \frac{\lambda^{(y_1+y_2)} e^{-2\lambda}}{y_1!y_2!} \mathbb{I}_{\{y_1 \geq 0, y_2 \geq 0\}}$$

Using the factorization for an exponential family, let  $\theta' = \log \lambda$

$$\begin{aligned} p_Y(y; \lambda) &= e^{\theta'(y_1+y_2)} \frac{e^{-2e^{\theta'}}}{y_1!y_2!} \\ \Rightarrow T(y) &= y_1 + y_2 \\ h(y) &= \frac{1}{y_1!y_2!} I_{\{y_1 \geq 0, y_2 \geq 0\}} \\ C(\theta') &= e^{-2e^{\theta'}} \end{aligned}$$

From the completeness theorem for exponential families,  $T(y) = y_1 + y_2$  is a complete sufficient statistic for  $\theta'$ . Since  $\theta$  and  $\theta'$  are in one-to-one correspondence, complete+sufficient for  $\theta'$  implies complete+sufficient for  $\theta$ .

(b) Recall that we want to estimate  $\theta = e^{-\lambda}$ .

$$\begin{aligned} \mathbf{E}_\theta \{ \hat{\theta}(Y) \} &= \frac{1}{2} \mathbf{E}_\theta \{ f(Y_1) + f(Y_2) \} \\ &= \frac{1}{2} \sum_{y_1=0}^{\infty} f(y_1) \frac{\lambda^{y_1} e^{-\lambda}}{y_1!} + \frac{1}{2} \sum_{y_2=0}^{\infty} f(y_2) \frac{\lambda^{y_2} e^{-\lambda}}{y_2!} \\ &= \frac{1}{2} \frac{\lambda^0 e^{-\lambda}}{0!} + \frac{1}{2} \frac{\lambda^0 e^{-\lambda}}{0!} \\ &= \frac{1}{2} e^{-\lambda} + \frac{1}{2} e^{-\lambda} = \theta \end{aligned}$$

Thus the estimator is **unbiased**.

(c) Using the RBL theorem,

$$\tilde{g}(y) = \mathbf{E}_\theta \left\{ \frac{1}{2} [f(Y_1) + f(Y_2)] \middle| T(Y) = y_1 + y_2 \right\}$$

In order to determine this MVUE we need the conditional pdfs  $p_{Y_i}(y_i; \lambda | T = t)$  for  $i = 1, 2$ . Using Bayes rule,

$$\begin{aligned} p_{Y_1}(y_1; \lambda | T = t) &= \frac{q(t; \lambda | y_1) p_{Y_1}(y_1; \lambda)}{q(t; \lambda)} = \frac{\Pr_\lambda \{ Y_2 = t - y_1 \} p_{Y_1}(y_1; \lambda)}{q(t; \lambda)} \\ &= \frac{\lambda^{(t-y_1)} e^{-\lambda}}{(t-y_1)!} \times \frac{\lambda^{y_1} e^{-\lambda}}{(y_1)!} \times \frac{t!}{(2\lambda)^t e^{-2\lambda}} \\ &= \left( \frac{1}{2} \right)^t \frac{t!}{(t-y_1)! y_1!} \\ \Rightarrow \mathbf{E}_\lambda \{ f(Y_1) | t \} &= \sum_{y_1=0}^{\infty} f(y_1) p(y_1; \lambda | t) = \left( \frac{1}{2} \right)^t \frac{t!}{(t-0)! 0!} = \left( \frac{1}{2} \right)^t \\ \mathbf{E}_\lambda \{ f(Y_2) | t \} &= \left( \frac{1}{2} \right)^t \text{ by same method.} \\ \Rightarrow \tilde{g}(T(y)) &= \left( \frac{1}{2} \right)^{(y_1+y_2)} \end{aligned}$$

By the RBL theorem we know that  $\tilde{g}$  is unbiased, and since  $\tilde{g}$  is a function of a complete

sufficient statistic we know that it must be MVUE. Verifying the unbiasedness (for fun):

$$\begin{aligned}\mathbf{E}_\lambda \{\tilde{g}(T)\} &= \sum_{t=0}^{\infty} \frac{(2\lambda)^t e^{-2\lambda}}{t!} \left(\frac{1}{2}\right)^t \\ &= e^{-2\lambda} \sum_{t=0}^{\infty} \frac{\lambda^t}{t!} = e^{-2\lambda} e^\lambda = e^{-\lambda} = \theta.\end{aligned}$$

(e) To determine the CRLB, we first calculate Fisher's information:

$$\begin{aligned}I(\theta) &= \mathbf{E}_\theta \left\{ -\frac{\partial^2}{\partial \theta^2} \log p(Y; \theta) \right\} \\ &= \mathbf{E}_\theta \left\{ \frac{1}{\theta^2} \left[ \frac{Y_1 + Y_2}{\log \theta} + 2 + \frac{Y_1 + Y_2}{(\log \theta)^2} \right] \right\} \\ \mathbf{E}_\theta \{Y_1 + Y_2\} &= 2\lambda = -2 \log \theta \\ \Rightarrow I(\theta) &= -\frac{2}{\theta^2 \log \theta}\end{aligned}$$

Finally, the CRLB for the variance of unbiased estimators of  $\theta$  is simply  $1/I_\theta$ .

5. 4 points. Suppose we have a polynomial fitting problem where the observed samples are given as

$$Y_k = \sum_{\ell=0}^{L-1} \theta_\ell k^\ell + W_k \text{ for } k = 0, 1, \dots, n-1$$

where  $W_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ . Find the Fisher information matrix for estimating  $\{\theta_0, \dots, \theta_{L-1}\}$ . If you have difficulty with the general case, try  $L = 2$  (fitting a straight line) first.

**Solution:** First consider the  $L = 2$  case. The  $2 \times 2$  Fisher information matrix is

$$I(\theta) = \begin{bmatrix} -\mathbf{E} \left[ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_0^2} \right] & -\mathbf{E} \left[ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_0 \partial \theta_1} \right] \\ -\mathbf{E} \left[ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_1 \partial \theta_0} \right] & -\mathbf{E} \left[ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_1^2} \right] \end{bmatrix}$$

where  $p(y; \theta) = \frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} e^{-\frac{1}{2\sigma^2} \sum_{k=0}^{n-1} (y_k - \theta_0 - \theta_1 k)^2}$ . Hence

$$\begin{aligned}\frac{\partial \ln p(y; \theta)}{\partial \theta_0} &= \frac{1}{\sigma^2} \sum_{k=0}^{n-1} (y_k - \theta_0 - \theta_1 k) \\ \frac{\partial \ln p(y; \theta)}{\partial \theta_1} &= \frac{1}{\sigma^2} \sum_{k=0}^{n-1} (y_k - \theta_0 - \theta_1 k) k \\ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_0^2} &= -\frac{n}{\sigma^2} \\ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_0 \partial \theta_1} &= -\frac{1}{\sigma^2} \sum_{k=0}^{n-1} k \\ \frac{\partial^2 \ln p(y; \theta)}{\partial \theta_1^2} &= -\frac{1}{\sigma^2} \sum_{k=0}^{n-1} k^2\end{aligned}$$

Accordingly, we have the Fisher information matrix as

$$I(\theta) = \frac{1}{\sigma^2} \begin{bmatrix} n & \sum_{k=0}^{n-1} k \\ \sum_{k=0}^{n-1} k & \sum_{k=0}^{n-1} k^2 \end{bmatrix}$$

from which we can draw a few bits of insight:

- Estimating the slope of a line is more difficult than estimating its intercept, since  $I_{22}(\theta) > I_{11}(\theta)$ . One source of intuition for this is that it takes at least two samples to estimate the slope, whereas it takes only one sample to estimate the intercept.
- An unknown intercept leads to an increase in the minimum variance of the slope, and vice-versa. This is intuitive since it would be easier to estimate the intercept or the slope if the other were known.

The same approach can be applied to the case when  $L > 2$ . You can get the Fisher information matrix for general  $L$  as

$$I(\theta) = \frac{1}{\sigma^2} \begin{bmatrix} n & \dots & \sum_{k=0}^{n-1} k^{L-1} \\ \vdots & \ddots & \vdots \\ \sum_{k=0}^{n-1} k^{L-1} & \dots & \sum_{k=0}^{n-1} k^{2(L-1)} \end{bmatrix}.$$

Once again, it is clear that the higher order coefficients are more difficult to estimate since their minimum variances are larger than the lower order coefficients.