

ECE531 Screencast 10.4: Minimum Error Probability Binary Signal Detection

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Minimum Probability of Error: Bayes Detection with UCA

Suppose we have a binary additive Gaussian noise detection problem with $x \in \{s_0, s_1\}$ and a given prior π_0 .

The probability of making an incorrect decision is (Bayes risk with UCA)

$$\begin{aligned} P_e &= \pi_0 \text{Prob}(\text{decide } \mathcal{H}_1 \mid x = s_0) + (1 - \pi_0) \text{Prob}(\text{decide } \mathcal{H}_0 \mid x = s_1) \\ &= \pi_0 \text{Prob}(\bar{s}^\top \bar{Y} \geq v' \mid x = s_0) + (1 - \pi_0) \text{Prob}(\bar{s}^\top \bar{Y} < v' \mid x = s_1) \end{aligned}$$

where v' is the decision threshold. For $\mu_j := (\bar{s}_1 - \bar{s}_0)^\top \bar{s}_j$, we can write

$$P_e = \pi_0 Q\left(\frac{v' - \mu_0}{\|\bar{s}\|}\right) + (1 - \pi_0) Q\left(\frac{\mu_1 - v'}{\|\bar{s}\|}\right)$$

and we know the decision threshold v' that minimizes P_e is

$$v' = \ln \frac{\pi_0}{1 - \pi_0} + \frac{1}{2} (\|\bar{s}_1\|^2 - \|\bar{s}_0\|^2)$$

Uniform Prior and Optimum Detection Threshold

Suppose that we have a uniform prior $\pi_0 = \pi_1 = \frac{1}{2}$ and that the optimum threshold for this prior, i.e. $v' = \frac{1}{2}(\|\bar{s}_1\|^2 - \|\bar{s}_0\|^2)$, is used by the detector.

Note that

$$v' = \frac{1}{2}(\|\bar{s}_1\|^2 - \|\bar{s}_0\|^2) = \frac{(\bar{s}_1 - \bar{s}_0)^\top \bar{s}_0 + (\bar{s}_1 - \bar{s}_0)^\top \bar{s}_1}{2} = \frac{\mu_0 + \mu_1}{2}$$

Hence, the probability of error can be written as

$$P_e = \frac{1}{2}Q\left(\frac{\mu_1 - \mu_0}{2\|\bar{s}\|}\right) + \frac{1}{2}Q\left(\frac{\mu_1 - \mu_0}{2\|\bar{s}\|}\right) = Q\left(\frac{\mu_1 - \mu_0}{2\|\bar{s}\|}\right)$$

We can also write

$$\mu_1 - \mu_0 = (\bar{s}_1 - \bar{s}_0)^\top \bar{s}_1 - (\bar{s}_1 - \bar{s}_0)^\top \bar{s}_0 = \|\bar{s}_0\|^2 + \|\bar{s}_1\|^2 - 2\bar{s}_0^\top \bar{s}_1 = \|\bar{s}\|^2$$

Hence

$$P_e = Q\left(\frac{\|\bar{s}\|}{2}\right)$$

Optimum Signal Design for Minimum Error Probability

In communication problems, we often can choose our signal alphabet. Since $Q(x)$ is monotonically decreasing in x , we should choose s_0 and s_1 to maximize $\|\bar{s}\|$. To get a useful result, we require the power of each signal s_0 and s_1 to be upper bounded by B , i.e.

$$\frac{1}{n}\|s_j\|^2 \leq B \quad \Rightarrow \quad \frac{1}{n}\|s_0 - s_1\|^2 \leq 4B$$

Recall $\bar{s} = (Ss_1 - Ss_0)$ with $\Sigma^{-1} = S^T S$. We can write

$$\|\bar{s}\|^2 = (Ss_1 - Ss_0)^T (Ss_1 - Ss_0) = (s_1 - s_0)^T \Sigma^{-1} (s_1 - s_0)$$

Let $\lambda_{max}(\Sigma^{-1})$ be the largest eigenvalue of the positive definite matrix Σ^{-1} and let ν be the eigenvector associated with this eigenvalue. Then

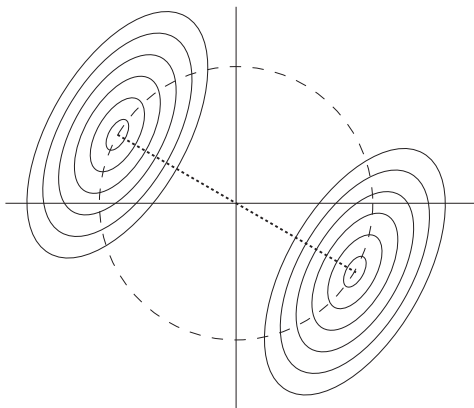
$$\|\bar{s}\|^2 \leq \lambda_{max}(\Sigma^{-1})\|s_1 - s_0\|^2$$

with equality only if $s_1 - s_0 = \alpha\nu$ for some scalar α . Hence

$$(s_1 - s_0)^T \Sigma^{-1} (s_1 - s_0) = \|\bar{s}\|^2 \leq 4nB\lambda_{max}(\Sigma^{-1}).$$

Optimum Signal Design: Geometric Interpretation

The probability of error is minimized when $s_1 - s_0$ is aligned with the eigenvector of $\Sigma^{-1} = 1/\lambda_{\min}(\Sigma)$ corresponding to the maximum eigenvalue $\lambda_{\max}(\Sigma^{-1})$ and arranged antipodally on the sphere of radius \sqrt{nB} .



Optimum Signal Design: Summary

- ▶ The probability of error is minimized when $s_1 - s_0$ is aligned with the eigenvector of Σ corresponding to the smallest eigenvalue $\lambda_{min}(\Sigma)$, i.e. $s_1 - s_0$ is aligned in the direction of least noise variance.
- ▶ The minimum achievable error probability with optimum signaling (and equiprobable signals) is then

$$P_e^* = Q\left(\frac{\|\bar{s}\|}{2}\right) = Q\left(\frac{\sqrt{4nB\lambda_{max}(\Sigma^{-1})}}{2}\right) = Q\left(\frac{\sqrt{nB}}{\sigma_{min}}\right)$$

where $\sigma_{min}^2 = \lambda_{min}(\Sigma)$.