

# ECE531 Screencast 12.1: Introduction to Deterministic Signal Detection with Unknown Parameters

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# Introduction

We now consider **parametric detection** problems for known/deterministic signals with **one or more unknown parameters**.

- ▶ We focus on the case of an  $N$ -sample discrete time observation  $Y \in \mathcal{Y}$  with binary hypotheses

$$\mathcal{H}_0 : Y \sim p_x(y) \text{ for } x \in \mathcal{X}_0$$

$$\mathcal{H}_1 : Y \sim p_x(y) \text{ for } x \in \mathcal{X}_1$$

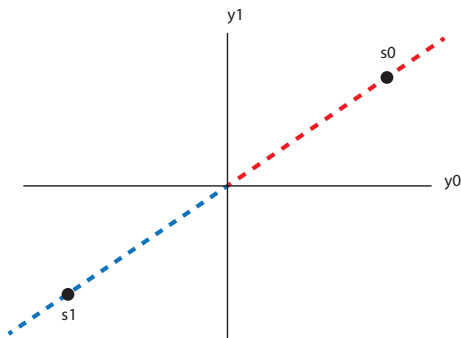
with  $\mathcal{X}_0 \cup \mathcal{X}_1 = \mathcal{X}$  and  $\mathcal{X}_0 \cap \mathcal{X}_1 = \emptyset$

- ▶ Our approach: Since we will have more than one state associated with one or both hypotheses, we will use our tools from **composite hypothesis testing** to develop good detectors.

# Example 1

Suppose we have a known signal  $s \in \mathbb{R}^n$  and we have a communication system that transmits either  $s_0 = -s$  or  $s_1 = s$ . The signal arrives with unknown amplitude  $a > 0$  and is corrupted by zero-mean AWGN with known variance  $\sigma^2$ .

For  $n = 2$ , we can illustrate this situation:



## Example 1 (continued)

A key step in these kinds of problems is to set them up correctly. If possible, we want to absorb the unknown parameter(s) into the state.

In this example, since  $s_1 = s = -s_0$ , we have

$$Y \sim \mathcal{N}(as, \sigma^2 I)$$

from any state  $a \in \mathcal{X}$  with  $a < 0$  when  $s_0$  is sent and  $a > 0$  when  $s_1$  is sent. If we let the state  $x = a$ , then the hypotheses can be written as

$$\mathcal{H}_0 : x < 0$$

$$\mathcal{H}_1 : x > 0$$

with the state space  $\mathcal{X} = \mathbb{R} \setminus 0$ .

This is a composite binary hypothesis testing problem with composite null and composite alternative hypotheses.

## Example 2

Suppose now we have a known signal  $s \in \mathbb{R}^n$  and we want to detect its presence or absence. The signal arrives with unknown amplitude  $a > 0$  and is corrupted by zero-mean AWGN with known variance  $\sigma^2$ .

As before, we have

$$Y \sim \mathcal{N}(as, \sigma^2 I)$$

from any state  $a \in \mathcal{X}$ . In this case, we can say  $a = 0$  when the signal is absent and  $a > 0$  when the signal is present. If we let the state  $x = a$ , then the hypotheses can be written as

$$\mathcal{H}_0 : x = 0$$

$$\mathcal{H}_1 : x > 0$$

with the state space  $\mathcal{X} = [0, \infty)$ .

This is a composite binary hypothesis testing problem with a simple null and a composite alternative hypotheses.

# Strategies for Finding Good Detectors

For these types of detection problems, we have three approaches:

1. N-P criterion with significance level  $\alpha$ :
  - ▶ Our strategy: **reduce the composite HT problem to a simple one.**
  - ▶ Check for the existence of a UMP decision rule (check the critical region and/or monotone likelihood ratio) that maximizes  $P_{D,x}$  for all  $x \in \mathcal{X}_1$  subject to  $P_{\text{fp},x} \leq \alpha$  for all  $x \in \mathcal{X}_0$ .
  - ▶ If a UMP rule doesn't exist, we can try to find an LMP decision rule.
2. Bayesian decision rule:
  - ▶ Need a prior on all of the states.
  - ▶ Need a cost assignment (typically the UCA).
  - ▶ Compute commodity costs  $g_i(y, \pi)$  and pick smallest.
3. GLRT decision rule:
  - ▶ Need to find MLE of the unknown parameter(s).
  - ▶ Plug in MLE estimates to make a simple hypothesis testing problem.
  - ▶ Suboptimal, but usually easier to compute than a Bayesian detector and usually gives good performance.