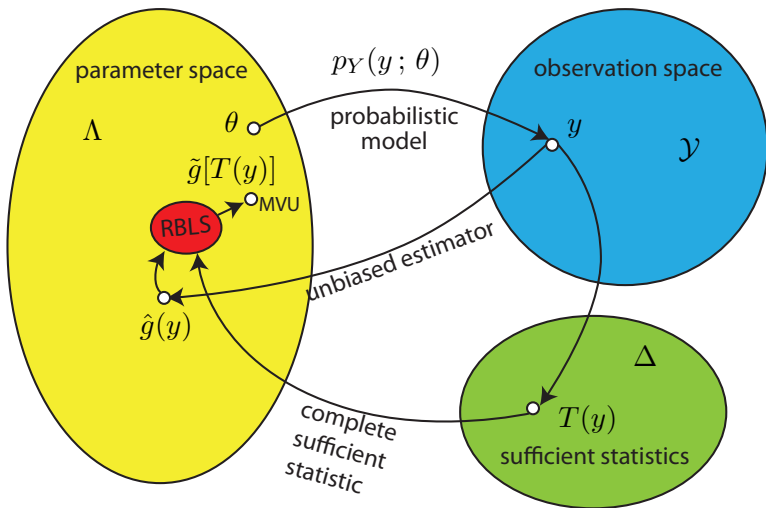


ECE531 Screencast 3.3: Introduction to the Rao-Blackwell-Lehmann-Sheffe Theorem

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Conceptual Model



RBLS: A Procedure for Finding MVU Estimators

To find an MVU estimator for the non-random parameter θ , we can follow a three-step procedure:

1. Find a **complete sufficient statistic** $T : \mathcal{Y} \rightarrow \Delta$ for the family of pdfs $\{p_Y(y; \theta); \theta \in \Lambda\}$ parameterized by θ .
2. Find *any* unbiased estimator $\hat{g}(y)$ of θ .
3. Compute $\tilde{g}[T(y)] = E[\hat{g}(Y) | T(Y) = T(y)]$.

The **Rao-Blackwell-Lehmann-Sheffe Theorem** says that $\tilde{g}[T(y)]$ will be a MVU estimator of the non-random parameter θ .

Some Intuition About Sufficient Statistics

Suppose we have observations given by

$$Y_k = \theta + W_k \quad k = 0, \dots, n-1$$

where $W_k \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$. We already know that

$$\hat{\theta}(y) = \frac{1}{n} \sum_{k=0}^{n-1} y_k$$

is a MVU estimator.

- ▶ The set of observations is $\mathcal{S} = \{y_0, \dots, y_{n-1}\}$.
- ▶ If we threw away some of the observations, would we still be able to compute the MVU estimator?
- ▶ What about these observation sets?

$$\mathcal{S}' = \{y_0\}$$

$$\mathcal{S}'' = \{y_0 + y_1, y_2, \dots, y_{n-1}\}$$

$$\mathcal{S}''' = \{y_0 + y_1 + \dots + y_{n-1}\}$$

Some Intuition About Sufficient Statistics

- ▶ The original set of observations is always a “sufficient statistic”. But there are often smaller sets that contain the **relevant** information.
- ▶ A sufficient statistic **summarizes** all of the information in the original set of observations so that, **if you condition the pdf of the observations on the sufficient statistic, the pdf no longer depends on the unknown parameter.**
- ▶ If you are given the sufficient statistic, you can ignore the observations. They contain no additional relevant information.
- ▶ There may be many different sufficient statistics.
- ▶ The sufficient statistic is not allowed to be a function of the unknown parameter θ . It may only be a function of the observations (and other known parameters, e.g. noise variance, number of observations, ...).