

Solution to Problem 1 : (Chen 5.11)

$$\dot{x} = \underbrace{\begin{bmatrix} -1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}}_A x$$

Test for "marginal" stability: Look at e-values of A
characteristic polynomial

$$\det(\lambda I_3 - A) = \det \begin{bmatrix} \lambda+1 & 0 & -1 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix} = (\lambda+1)\lambda^2$$

we have one e-value at $\lambda_1 = -1$ and two at $\lambda_2 = 0$

$$r_1 = 1, r_2 = 2$$

The e-value at $\lambda_1 = -1$ is no problem but the pair of e-values at $\lambda_2 = 0$ is a problem - we need to check that $m_2 = r_2$ (the geometric multiplicity equals the algebraic multiplicity for the λ_2 e-value).

$$E(\lambda_2) = \text{nullspace}(A - \lambda_2 I_3) = \text{nullspace}(A)$$

A is already in echelon form hence a basis for the nullspace follows naturally as

$$B_2 = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

Since we have a 1 dimensional basis $m_2 = 1 \neq r_2$.

\Rightarrow A is not "marginally" stable.

Note that A is not asymptotically stable since A is not marginally stable.

Solution to Problem 2 : Chen 5.12

$$x(k+1) = \begin{bmatrix} 0.9 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} x(k)$$

Test for "marginal" stability: Again look at e-values of A

we see that $\lambda_1 = 0.9, \lambda_2 = 1$ $\underbrace{r_1 = 1, r_2 = 2}_{\text{algebraic multiplicities}}$

Note that λ_1 is no problem but the repeated e-value $\lambda_2 = 1$ might be. Need to check geometric multiplicity of λ_2 .

$$E(\lambda_2) = \text{null}(A - \lambda_2 I_3) = \text{null}\left(\begin{bmatrix} -0.1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right)$$

$$\text{A basis for } E(\lambda_2) \text{ is } B_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

$$\dim(E(\lambda_2)) = m_2 = 2$$

and since $m_2 = r_2$, this system is "marginally" stable.

This system is not asymptotically stable due to the e-value $\lambda_2 = 1$.

Solution to Problem 3: Chen 5.14

$$A = \begin{bmatrix} 0 & 1 \\ -0.5 & -1 \end{bmatrix}$$

We need to use the Lyapunov stability Theorem to show that the e-values of A have negative real parts.

We will use Lyapunov Lemma II which says that if

$$A^T P + P A = -Q$$

has a ^{unique} positive definite solution for P for any particular positive definite Q , then A 's e-values have negative real parts.

$$\text{Let } Q = I_2$$

Then we must find $P_{11}, P_{12}, P_{21}, P_{22}$ satisfying

$$\begin{bmatrix} 0 & -0.5 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} + \begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -0.5 & -1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

To solve this, first simplify the LHS

$$\begin{bmatrix} -\frac{1}{2} P_{21} & -\frac{1}{2} P_{22} \\ P_{11} - P_{21} & P_{12} - P_{22} \end{bmatrix} + \begin{bmatrix} -\frac{1}{2} P_{12} & P_{11} - P_{12} \\ -\frac{1}{2} P_{22} & P_{21} - P_{22} \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

hence, equating (i, j) th entries, we have 4 equations:

$$a) \quad -\frac{1}{2}P_{21} - \frac{1}{2}P_{12} = -1$$

$$b) \quad -\frac{1}{2}P_{22} + P_{11} - P_{12} = 0$$

$$c) \quad P_{11} - P_{21} - \frac{1}{2}P_{22} = 0$$

$$d) \quad P_{12} + P_{21} - 2P_{22} = -1$$

Since solution for P must be positive definite, we require symmetry hence $P_{21} = P_{12}$. We can solve a) immediately then

$$-\frac{1}{2}P_{21} - \frac{1}{2}P_{12} = -1 \Rightarrow P_{12} = P_{21} = 1$$

$$\text{Then equation d) } \Rightarrow -2P_{22} = -3, P_{22} = \frac{3}{2}$$

$$\text{then equation b) } \Rightarrow P_{11} = 1 + \frac{1}{2} \cdot \frac{3}{2} = \frac{7}{4}$$

Note that equation c) is also satisfied now.

$$\text{hence } P = \begin{bmatrix} 7/4 & 1 \\ 1 & 3/2 \end{bmatrix} \text{ which satisfies the symmetry property but is it positive definite?}$$

brute force...

$$\det(\lambda I - P) = \det \left(\begin{bmatrix} \lambda - 7/4 & -1 \\ -1 & \lambda - 3/2 \end{bmatrix} \right) = (\lambda - \frac{7}{4})(\lambda - \frac{3}{2}) - 1$$

$$= \lambda^2 - \frac{13}{4}\lambda + \frac{21}{8} - 1 = \lambda^2 - \frac{13}{4}\lambda + \frac{13}{8}$$

roots of this quadratic equation are

$$\frac{\frac{13}{4} \pm \sqrt{\left(\frac{13}{4}\right)^2 - \frac{13}{2}}}{2} = \frac{\frac{13}{4} \pm \sqrt{\frac{169}{16} - \frac{104}{16}}}{2}$$

$$= \frac{\frac{13}{4} \pm \sqrt{\frac{65}{16}}}{2} = \frac{13}{8} \pm \frac{\sqrt{65}}{8}$$

Since $\sqrt{65} < 13$ then both roots are positive

and P is positive definite. Unique positive definite P implies that A is then Hurwitz.

(Note that there are easier ways to show P is positive defn...)

Solution to Problem 4.

$$A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

use Lyapunov stability theorem

$$P - A^T P A = Q, \text{ let } Q = I_2$$

Then

$$\begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

just pull out the $\frac{1}{2}$ terms

simplify...

$$\begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} P_{11} - P_{12} & P_{11} + P_{12} \\ P_{21} - P_{22} & P_{21} + P_{22} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} - \frac{1}{4} \begin{bmatrix} P_{11} - P_{12} - P_{21} + P_{22} & P_{11} + P_{12} - P_{21} - P_{22} \\ P_{11} - P_{12} + P_{21} - P_{22} & P_{11} + P_{12} + P_{21} + P_{22} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

equate (i, j)th terms:

$$\frac{3}{4} P_{11} + \frac{1}{4} P_{12} + \frac{1}{4} P_{21} - \frac{1}{4} P_{22} = 1$$

$$-\frac{1}{4} P_{11} + \frac{3}{4} P_{12} + \frac{1}{4} P_{21} + \frac{1}{4} P_{22} = 0$$

$$-\frac{1}{4} P_{11} + \frac{1}{4} P_{12} + \frac{3}{4} P_{21} + \frac{1}{4} P_{22} = 0$$

$$-\frac{1}{4} P_{11} - \frac{1}{4} P_{12} - \frac{1}{4} P_{21} + \frac{3}{4} P_{22} = 1$$

Use Matlab to solve...

$$\begin{aligned} P_{11} &= \frac{1}{2} \\ P_{12} &= P_{21} = 0 \\ P_{22} &= \frac{1}{2} \end{aligned} \Rightarrow P = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

P clearly positive definite and unique, hence A is Hurwitz.
(as expected)



Now look at $A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$, use prior analysis to write:

$$\begin{bmatrix} P_{11} & P_{12} \\ P_{21} & P_{22} \end{bmatrix} - \begin{bmatrix} P_{11} - P_{12} - P_{21} + P_{22} & P_{11} + P_{12} - P_{21} - P_{22} \\ P_{11} - P_{12} + P_{21} - P_{22} & P_{11} + P_{12} + P_{21} + P_{22} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

equate (i, j)th terms:

$$\begin{aligned} P_{12} + P_{21} - P_{22} &= 1 \\ -P_{11} + P_{21} + P_{22} &= 0 \\ -P_{11} + P_{12} + P_{22} &= 0 \\ -P_{11} - P_{12} - P_{21} &= 1 \end{aligned}$$

$$\underbrace{\begin{bmatrix} 0 & 1 & 1 & -1 \\ -1 & 0 & 1 & 1 \\ -1 & 1 & 0 & 1 \\ -1 & -1 & -1 & 0 \end{bmatrix}}_X \begin{bmatrix} P_{11} \\ P_{12} \\ P_{21} \\ P_{22} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

X is invertible, so unique soln exists,

$$\left. \begin{aligned} P_{11} &= -1 \\ P_{12} &= 0 \\ P_{21} &= 0 \\ P_{22} &= -1 \end{aligned} \right\} \Rightarrow P = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

P not positive definite hence A not Hurwitz.
(as expected)

Solution to problem 5:

$$x(k+1) = \underbrace{\begin{bmatrix} \cos \theta & \sin \frac{\theta}{2} \\ -\sin \frac{\theta}{2} & \cos \theta \end{bmatrix}}_A x(k)$$

Lets look at asymptotic stability first. Find the e-values of A.

$$\begin{aligned} \det(\lambda I_2 - A) &= (\lambda - \cos \theta)^2 + \sin^2 \frac{\theta}{2} \\ &= \lambda^2 - 2\lambda \cos \theta + \cos^2 \theta + \sin^2 \frac{\theta}{2} \end{aligned}$$

quadratic equation, roots:

$$\begin{aligned} \text{roots} &= \frac{2\cos \theta \pm \sqrt{4\cos^2 \theta - 4\cos^2 \theta - 4\sin^2 \frac{\theta}{2}}}{2} \\ &= \frac{2\cos \theta \pm j2\sin \frac{\theta}{2}}{2} = \cos \theta \pm j\sin \frac{\theta}{2} \end{aligned}$$

what values of θ cause both roots $\cos \theta + j\sin \frac{\theta}{2} = \lambda_1$
 $\cos \theta - j\sin \frac{\theta}{2} = \lambda_2$

to have magnitude less than one?

Since both roots have same magnitude, we just need to look at one of them.

$$|\cos \theta + j\sin \frac{\theta}{2}| = \sqrt{\cos^2 \theta + \sin^2 \frac{\theta}{2}} < 1$$

square both sides

$$\cos^2 \theta + \sin^2 \frac{\theta}{2} < 1$$

trig identity $\sin^2 \alpha = \frac{1}{2}(1 - \cos 2\alpha)$ hence

$$\cos^2 \theta + \frac{1}{2}(1 - \cos \theta) < 1 \Leftrightarrow \cos^2 \theta - \frac{1}{2}\cos \theta + \frac{1}{2} < 1$$

$$\cos^2 \theta - \frac{1}{2}\cos \theta < \frac{1}{2} \Leftrightarrow \cos^2 \theta - \frac{1}{2}\cos \theta + \frac{1}{16} < \frac{1}{2} + \frac{1}{16}$$

$$\left(\cos \theta - \frac{1}{4}\right)^2 < \frac{1}{2} + \frac{1}{16} \Leftrightarrow \left(\cos \theta - \frac{1}{4}\right)^2 < \frac{9}{16}$$

$$-\sqrt{\frac{9}{16}} < \cos \theta - \frac{1}{4} < \sqrt{\frac{9}{16}}$$

$$-\frac{1}{2} < \cos \theta < 1$$

hence, since $\cos \theta = 1$ only when $\theta = 0$ (in our range of $\theta \in [0, 2\pi)$) then we have asymptotic stability when

$$\theta \in (0, \cos^{-1}(-\frac{1}{2}))$$

and by symmetry

$$\theta \in (2\pi - \cos^{-1}(-\frac{1}{2}), 2\pi).$$

"Marginal" stability is satisfied at all of these points also but we need to check the points

$$\theta = \{0, \cos^{-1}(-\frac{1}{2}), 2\pi - \cos^{-1}(-\frac{1}{2})\}$$

When $\theta = 0$, $A = I_2$, repeated e-values but diagonalizable, hence "marginally" stable.

When $\theta = \cos^{-1}(-\frac{1}{2})$, $A = \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$

in this case A has 2 distinct evalues $\lambda_1 = -\frac{1}{2} + j \frac{\sqrt{3}}{2}$
 $\lambda_2 = -\frac{1}{2} - j \frac{\sqrt{3}}{2}$

both have magnitude equal to one but $m_1 = r_1$ and $m_2 = r_2$ hence "marginally stable".

When $\theta = 2\pi - \cos^{-1}(-\frac{1}{2})$, $A = \begin{bmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$ same as prior case.

Hence system is "marginally" stable for $\theta \in [0, \cos^{-1}(-\frac{1}{2})]$
and $\theta \in [2\pi - \cos^{-1}(-\frac{1}{2}), 2\pi)$.

end of solution

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